

# OpenSS7 STREAMS Sockets Installation and Reference Manual

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Version 0.9.2 Edition 4  
Updated 2008-10-31  
Package strsock-0.9.2.4

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The OpenSS7 Project <<http://www.openss7.org/>>

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# Preface

## Notice

This package is released and distributed under the *AGPL* (see [GNU Affero General Public License], page 102). Please note, however, that there are different licensing terms for the manual pages and some of the documentation (derived from OpenGroup<sup>1</sup> publications and other sources). Consult the permission notices contained in the documentation for more information.

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## Abstract

This manual provides a *Installation and Reference Manual for OpenSS7 STREAMS Sockets*.

## Objective

The objective of this manual is to provide a guide for the *STREAMS* programmer when developing *STREAMS* modules, drivers and application programs for *OpenSS7 STREAMS Sockets*.

This guide provides information to developers on the use of the *STREAMS* mechanism at user and kernel levels.

*STREAMS* was incorporated in UNIX System V Release 3 to augment the character input/output (I/O) mechanism and to support development of communication services.

*STREAMS* provides developers with integral functions, a set of utility routines, and facilities that expedite software design and implementation.

## Intent

The intent of this manual is to act as an introductory guide to the *STREAMS* programmer. It is intended to be read alone and is not intended to replace or supplement the *OpenSS7 STREAMS Sockets* manual pages. For a reference for writing code, the manual pages (see **STREAMS(9)**) provide a better reference to the programmer. Although this describes the features of the *OpenSS7 STREAMS Sockets* package, **OpenSS7 Corporation** is under no obligation to provide any software, system or feature listed herein.

## Audience

This manual is intended for a highly technical audience. The reader should already be familiar with *Linux* kernel programming, the *Linux* file system, character devices, driver input and output, interrupts, software interrupt handling, scheduling, process contexts, multiprocessor locks, etc.

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<sup>1</sup> Formerly X/Open and UNIX International.

The guide is intended for network and systems programmers, who use the *STREAMS* mechanism at user and kernel levels for *Linux* and *UNIX* system communication services. Readers of the guide are expected to possess prior knowledge of the *Linux* and *UNIX* system, programming, networking, and data communication.

## Revisions

Take care that you are working with a current version of this manual: you will not be notified of updates. To ensure that you are working with a current version, contact the [Author](#), or check [The OpenSS7 Project](#) website for a current version.

A current version of this manual is normally distributed with the *OpenSS7 STREAMS Sockets* package, `strsock-0.9.2.4`.<sup>2</sup>

## Version Control

```
strsock.texi,v
Revision 0.9.2.16  2008-09-20 11:04:39  brian
- added package patchlevel

Revision 0.9.2.15  2008-08-03 06:03:38  brian
- protected agains texinfo commands in log entries

Revision 0.9.2.14  2008/07/27 08:49:41  brian
- no invariant sections, more libtool ignores

Revision 0.9.2.13  2008-04-28 22:33:30  brian
- updated headers for release

Revision 0.9.2.12  2008-04-25 11:50:54  brian
- updates to GPLv3

Revision 0.9.2.11  2007/08/12 06:45:02  brian
- updated licenses in manuals

Revision 0.9.2.10  2007/06/23 01:38:27  brian
- updates for release

Revision 0.9.2.9   2007/02/28 06:31:28  brian
- updates and corrections, #ifdef instead of #if

Revision 0.9.2.8   2006/09/18 01:07:16  brian
- updated manuals and release texi docs

Revision 0.9.2.7   2006/09/01 08:55:40  brian
- added headers and working up code

Revision 0.9.2.6   2006/08/29 11:44:05  brian
- added manual pages, working up docs

Revision 0.9.2.5   2006/08/28 10:47:10  brian
- correction

Revision 0.9.2.4   2006/08/28 10:32:58  brian
- updated references
```

---

<sup>2</sup> <http://www.openss7.org/tarballs/strsock-0.9.2.4.tar.bz2>

Revision 0.9.2.3 2006/08/27 12:27:12 brian  
- finalizing auto release files

Revision 0.9.2.2 2006/08/26 09:19:22 brian  
- better release file generation

Revision 0.9.2.1 2006/08/23 10:03:59 brian  
- started STREAMS Sockets package

## ISO 9000 Compliance

Only the  $\text{T}_{\text{E}}\text{X}$ , texinfo, or roff source for this manual is controlled. An opaque (printed, postscript or portable document format) version of this manual is an **UNCONTROLLED VERSION**.

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## Acknowledgements

As with most open source projects, this project would not have been possible without the valiant efforts and productive software of the *Free Software Foundation* and the *Linux Kernel Community*.

## Sponsors

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- OpenSS7 Corporation

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- SysMaster Corporation
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- TECORE
- Tumsan Oy
- Vodare Ltd.
- Excel Telecommunications

## Contributors

The primary contributor to the *OpenSS7 OpenSS7 STREAMS Sockets* package is **Brian F. G. Bidulock**. The following is a list of significant contributors to *The OpenSS7 Project*:

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- Tom Chandler
- Gurol Ackman
- Kutluk Testicioglu
- John Wenker
- Others

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– Brian Bidulock

See [Index of Authors], page 145, for a complete listing and cross-index of authors to sections of this manual.

## Maintainer

The maintainer of the *OpenSS7 OpenSS7 STREAMS Sockets* package is:

– Brian Bidulock

Please send bug reports to [bugs@openss7.org](mailto:bugs@openss7.org) using the ‘send-pr’ script included in the package, only after reading the ‘BUGS’ file in the release, or See Section 7.2 [Problem Reports], page 93.

## Web Resources

The [OpenSS7 Project](#) provides a website dedicated to the software packages released by the [OpenSS7 Project](#).

## Bug Reports

Please send bug reports to [bugs@openss7.org](mailto:bugs@openss7.org) using the ‘send-pr’ script included in the *OpenSS7 STREAMS Sockets* package, only after reading the ‘BUGS’ file in the release, or See Section 7.2 [Problem Reports], page 93. You can access the [OpenSS7 GNATS database](#) directly via the web, however, the preferred method for sending new bug reports is via mail with the ‘send-pr’ script.

## Mailing Lists

The [OpenSS7 Project](#) provides a number of general discussion [Mailing Lists](#) for discussion concerning the *OpenSS7 OpenSS7 STREAMS Sockets* package as well as other packages released by [The OpenSS7 Project](#).

These are mailman mailing lists and so have convenient web interfaces for subscribers to control their settings. See <http://www.openss7.org/maillinglist.html>.

The mailing lists are as follows:

‘[openss7](#)’ The ‘[openss7](#)’ mailing list is for general enquiries, information exchange and announcements regarding the [OpenSS7 Project](#). This is our original mailing list and takes the highest amount of traffic.

‘[openss7-announce](#)’

The ‘[openss7-announce](#)’ mailing list is for announcements related to the [OpenSS7 Project](#). This list will accept announcements posted by subscribers. Subscribe to this list if you are interested in announcements from the [OpenSS7 Project](#), subscribers and sponsors, related to the [OpenSS7 Project](#) or STREAMS, SS7, SIGTRAN or SCTP in general.

‘[openss7-cvs](#)’

The ‘[openss7-cvs](#)’ mailing list is for automatic CVS log reporting. You must get permission of the owner to subscribe to this list. Subscribers are not allowed to post to this list, this is merely for distributing notification of changes to the CVS repository.h

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The ‘openss7-develop’ mailing list is for email exchange related to the development projects under the [OpenSS7 Project](#). This includes development requests, proposals, requests for comment or proposal. Subscribe to this list if you are interested in ongoing development details regarding the [OpenSS7 Project](#).

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The ‘openss7-bugs’ mailing list is specifically tailored to bug tracking. The mailing list takes a feed from the [OpenSS7 GNATS](#) bug tracking system and accepts posting of responses to bug reports, tracking and resolution. Subscribe to this list if you are interested in receiving detailed *OpenSS7* release code bug tracking information. This list is not archived; for historical information on problem reports, see our [GNATS databases](#).

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**‘linux-streams’**

The ‘linux-streams’ mailing list is for mail exchange related to *Linux Fast-STREAMS* or *Linux STREAMS*. This includes patches, development requests, proposals, requests for comment or proposal. Subscribe to this list if you are interested in ongoing development details regarding the *STREAMS* for Linux components. This is the the new (September 2006) home of the ‘linux-streams’ list formerly of [gsyc.escet.urjc.es](#).

## Spam

To avoid spam being sent to the members of the *OpenSS7* mailing list(s), we have blocked mail from non-subscribers. Please subscribe to the mailing list before attempting to post to them. (Attempts to post when not subscribed get bounced.)

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### **Large Attachments**

The mailing list is blocked from messages of greater than 40k. If you have attachments (patches, test programs, etc.) and you mail them to the list, it will bounce to the list administrator. If you are interested in making your patches, test programs, test results or other large attachments available to the members of the mailing list, state in the message that you would like them posted and the list administrator will place them in the mail archives.





## Quick Start Guide

### OpenSS7 STREAMS Sockets

Package strsock-0.9.2.4 was released under AGPLv3 2008-10-31.

The *OpenSS7 STREAMS Sockets* package provides *STREAMS* modules and drivers, libraries, programs, initialization scripts, and daemons.

The *OpenSS7 STREAMS Sockets* package contains header files and a number of modules and drivers and the associated documentation originally contained in the *Linux Fast-STREAMS* release, but not contained in the *Linux STREAMS (LiS)* releases.

The package uses the following standard *Open Systems Interconnect (OSI)* conforming header files from the ‘strxnet’ package:

- ‘<sys/tiuser.h>’ *Transport Provider Interface (TPI)*
- ‘<sys/tihdr.h>’ *Transport Provider Interface (TPI)*

The package currently provides the following *STREAMS* modules and drivers:

- ‘streams\_sockmod.ko’ *module*
- ‘streams\_socksys.ko’ *‘/dev/socksys’*

- **sockmod(4)** The **sockmod(4)** module, when pushed on a *TPI Stream*, attempts to provide as wide a range of support for traditional *SVR 4.2* socket module and socket system support.

It does so by recognizing input-output controls from three sets:

**sockmod(4)** input-output controls; **socksys(4)** input-output controls, and even **socket(7)** system calls.

- **socksys(4)** The **socksys(4)** driver, when opened, provides a *TPI Stream* that attempts to provide as wide a range of support for traditional *SVR 4.2* socket module and socket system support.

It does so by recognizing input-output controls from three sets:

**sockmod(4)** input-output controls; **socksys(4)** input-output controls, and even **socket(7)** system calls.

The package currently provides the following *STREAMS* libraries:

- ‘libsocket.so’ ‘libsocket.a’
- ‘libsocklib.so’ ‘libsocklib.a’

The ‘libsocket’ library implements the following library calls:

**socket(3)**

The ‘libsocket’ library only needs to implement the single library call because file descriptors that are returned from the **socket(3)** call have been transformed into real sockets (from the viewpoint of the system call interface) and standard ‘glibc’ calls for the remaining functions are used.

The ‘libsocklib’ library implements the following library calls:

<b>accept(3)</b>	<b>listen(3)</b>	<b>sendto(3)</b>
<b>bind(3)</b>	<b>recv(3)</b>	<b>setsockopt(3)</b>
<b>connect(3)</b>	<b>recvfrom(3)</b>	<b>shutdown(3)</b>

<code>getpeername(3)</code>	<code>recvmsg(3)</code>	<code>socket(3)</code>
<code>getsockname(3)</code>	<code>send(3)</code>	<code>socketpair(3)</code>
<code>getsockopt(3)</code>	<code>sendmsg(3)</code>	

The ‘`libsocklib`’ library is the older compatibility library approach to providing sockets for *STREAMS* and implements the system calls as library calls for *STREAMS* devices, while calling the ‘`glibc`’ versions for true sockets.

The *OpenSS7 STREAMS Sockets* package includes kernel modules, *SVR 4.2 STREAMS* drivers, modules, libraries, utilities, test programs, daemons, and development environment for the development and execution of *OpenSS7 STREAMS Sockets* modules and drivers.

This distribution is only currently applicable to *Linux* 2.4 and 2.6 kernels and was targeted at `ix86`, `x86_64`, `ppc` and `ppc64` architectures, but should build and install for other architectures as well.

## Release

This is the `strsock-0.9.2.4` package, released 2008-10-31. This ‘0.9.2.4’ release, and the latest version, can be obtained from the [download area](#) of [The OpenSS7 Project](#) website using a command such as:

```
$> wget http://www.openss7.org/tarballs/strsock-0.9.2.4.tar.bz2
```

The release is available as an `autoconf(1)` tarball, ‘`src.rpm`’ or ‘`dsc`’, as a set of binary ‘`rpm`’s or ‘`deb`’s, or as a `yum(8)` or `apt(8)` repository. See the [download page](#) for the `autoconf(1)` tarballs, ‘`src.rpm`’s, ‘`dsc`’s, or repository access instructions. See the [strsock package page](#) for tarballs, source and binary packages.

Please see the ‘`NEWS`’ file for release notes and history of user visible changes for the current version, and the ‘`ChangeLog`’ file for a more detailed history of implementation changes. The ‘`TODO`’ file lists features not yet implemented and other outstanding items.

Please see the ‘`INSTALL`’, ‘`INSTALL-strsock`’ and ‘`README-make`’, files (or see [Chapter 6 \[Installation\]](#), page 43) for installation instructions.

When working from `cvs(1)` or `git(1)`, please see the ‘`README-cvs`’, file (or see [Section 6.2.8 \[Downloading from CVS\]](#), page 55). An abbreviated installation procedure that works for most applications appears below.

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See ‘`README-alpha`’ (if it exists) for alpha release information.

## Prerequisites

The quickest and easiest way to ensure that all prerequisites are met is to download and install this package from within the *OpenSS7 Master Package*, `openss7-0.9.2.G`, instead of separately.

Prerequisites for the *OpenSS7 STREAMS Sockets* package are as follows:

1. *Linux* distribution, somewhat *Linux Standards Base* compliant, with a 2.4 or 2.6 kernel and the appropriate tool chain for compiling out-of-tree kernel modules. Most recent

Linux distributions are usable out of the box, but some development packages must be installed. For more information, see [Section 5.2 \[Compatibility\]](#), page 34.

- A fairly LSB compliant GNU/Linux distribution.<sup>1</sup>
- Linux 2.4 kernel (2.4.10 - 2.4.27), or
- Linux 2.6 kernel (2.6.3 - 2.6.26);
- glibc2 or better.
- GNU groff (for man pages).<sup>2</sup>
- GNU texinfo (for info files).

(Note: If you acquired `strsock` a part of the *OpenSS7 Master Package*, then the dependencies listed below will already have been met by unpacking the master package.)

2. *OpenSS7 Linux Fast-STREAMS*, `streams-0.9.2.4`.<sup>3</sup>
3. *OpenSS7 STREAMS Compatibility Modules*, `strcompat-0.9.2.7`.
4. *OpenSS7 STREAMS XNS*, `strxns-0.9.2.7`.
5. *OpenSS7 STREAMS XTI/TLI*, `strxnet-0.9.2.12`.

When configuring and building multiple *OpenSS7 Project* release packages, place all of the source packages (unpacked tarballs) at the same directory level and all build directories at the same directory level (e.g. all source packages under `‘/usr/src’`).

When installing packages that install as kernel modules, it is necessary to have the correct kernel development package installed. For the following distributions, use the following commands:

```
Ubuntu:  $> apt-get install linux-headers
Debian:  $> apt-get install kernel-headers
Fedora:  $> yum install kernel-devel
```

You also need the same version of `gcc(1)` compiler with which the kernel was built. If it is not the default, add `‘CC=kgcc’` on the line after `‘./configure’`, for example:

```
$> ../strsock-0.9.2.4/configure CC='gcc-3.4'
```

## Installation

The following commands will download, configure, build, check, install, validate, uninstall and remove the package:

```
$> wget http://www.openss7.org/tarballs/strsock-0.9.2.4.tar.bz2
$> tar -xjvf strsock-0.9.2.4.tar.bz2
$> mkdir build
$> pushd build
$> ../strsock-0.9.2.4/configure --enable-autotest
$> make
$> make check
$> sudo make install
$> sudo make installcheck
```

<sup>1</sup> See [Section 5.2.1 \[GNU/Linux Distributions\]](#), page 34, for more information.

<sup>2</sup> If you are using a Debian release, please make sure to install the groff extension package (`‘groff_ext’`), as it contains the `refer` or `grefer` commands necessary for including references in the manual pages.

<sup>3</sup> Although, at one time, this package supported *LiS*, *LiS* is now deprecated and unsupported.

```

$> sudo make uninstall
$> popd
$> sudo rm -rf build
$> rm -rf strsock-0.9.2.4
$> rm -f strsock-0.9.2.4.tar.bz2

```

If you have problems, try building with the logging targets instead. If the make of a logging target fails, an automatic problem report will be generated that can be mailed to [The OpenSS7 Project](#).<sup>4</sup> Installation steps using the logging targets proceed as follows:

```

$> wget http://www.openss7.org/tarballs/strsock-0.9.2.4.tar.bz2
$> tar -xjvf strsock-0.9.2.4.tar.bz2
$> mkdir build
$> pushd build
$> ../strsock-0.9.2.4/configure --enable-autotest
$> make compile.log
$> make check.log
$> sudo make install.log
$> sudo make installcheck.log
$> sudo make uninstall.log
$> popd
$> sudo rm -rf build
$> rm -rf strsock-0.9.2.4
$> rm -f strsock-0.9.2.4.tar.bz2

```

See [‘README-make’](#) for additional specialized make targets.

For custom applications, see the [‘INSTALL’](#) and [‘INSTALL-strsock’](#) files or the see [Chapter 6 \[Installation\]](#), page 43, as listed below. If you encounter troubles, see [Chapter 7 \[Troubleshooting\]](#), page 89, before issuing a bug report.

## Brief Installation Instructions

The OpenSS7 STREAMS Sockets package is available from the [downloads area of The OpenSS7 Project website](#) using a command such as:

```

$> wget http://www.openss7.org/tarballs/strsock-0.9.2.4.tar.bz2

```

Unpack the tarball using a command such as:

```

$> tar -xjvf strsock-0.9.2.4.tar.bz2

```

The tarball will unpack into the relative subdirectory named after the package name: `strsock-0.9.2.4`.

The package builds using the GNU `autoconf` utilities and the `configure` script. To build the package, we recommend using a separate `build` directory as follows:

```

$> mkdir build
$> cd build
$> ../strsock-0.9.2.4/configure

```

---

<sup>4</sup> Please see [Section 7.2 \[Problem Reports\]](#), page 93, or the file [‘PROBLEMS’](#) in the release directory for more information on filing a proper *Problem Report*.

In general, the package configures and builds without adding any special options to the ‘configure’ script. For general options to the ‘configure’ script, see the GNU ‘INSTALL’ file in the distribution:

```
$> less ../strsock-0.9.2.4/INSTALL
```

For specific options to the ‘configure’ script, see the ‘INSTALL-strsock’ file in the distribution, or simply execute the configure script with the ‘--help’ option like so:

```
$> ../strsock-0.9.2.4/configure --help
```

After configuring the package, the package can be compiled simply by issuing the ‘make’ command:

```
$> make
```

Some specialized makefile targets exists, see the ‘README-make’ file in the distribution or simply invoke the ‘help’ target like so:

```
$> make help | less
```

After successfully building the package, the package can be checked by invoking the ‘check’ make target like so:

```
$> make check
```

After successfully checking the package, the package can be installed by invoking the ‘install’ make target (as root) like so:

```
$> sudo make install
```

The test suites that ship with the package can be invoked after the package has been installed by invoking the ‘installcheck’ target. This target can either be invoked as root, or as a normal user, like so:

```
$> make installcheck
```

(Note: you must add the ‘--enable-autotest’ flag to ‘configure’, above for the test suites to be invoked with ‘make installcheck’.)

The package can be cleanly removed by invoking the ‘uninstall’ target (as root):

```
$> sudo make uninstall
```

Then the build directory and tarball can be simply removed:

```
$> cd ..  
$> rm -rf build  
$> rm -rf strsock-0.9.2.4  
$> rm -f strsock-0.9.2.4.tar.bz2
```

## Detailed Installation Instructions

More detailed installation instructions can be found in the [Chapter 6 \[Installation\]](#), page 43, contained in the distribution in ‘text’, ‘info’, ‘html’ and ‘pdf’ formats:

```
$> cd ../strsock-0.9.2.4  
$> less doc/manual/strsock.txt  
$> lynx doc/manual/strsock.html  
$> info doc/manual/strsock.info  
$> xpdf doc/manual/strsock.pdf
```

The ‘text’ version of the manual is always available in the ‘MANUAL’ file in the release.

The current manual is also always available online from *The OpenSS7 Project* website at:

```
$> lynx http://www.openss7.org/strsock\_manual.html
```

# 1 Introduction

This manual documents the design, implementation, installation, operation and future development schedule of the *OpenSS7 STREAMS Sockets* package.

## 1.1 Overview

This manual documents the design, implementation, installation, operation and future development of the *OpenSS7 STREAMS Sockets* package.

## 1.2 Organization of this Manual

This manual is organized (loosely) into several sections as follows:

Chapter 1 [Introduction], page 15.	This introduction
Chapter 2 [Objective], page 17.	Objective of the package
Chapter 3 [Reference], page 25.	Contents of the package
Chapter 4 [Conformance], page 31.	Conformance of the package
Chapter 5 [Releases], page 33.	Releases of the package
Chapter 6 [Installation], page 43.	Installation of the package
Chapter 7 [Troubleshooting], page 89.	Troubleshooting of the package

## 1.3 Conventions and Definitions

This manual uses *texinfo* typographic conventions.





## 2 Objective

The objective of the *OpenSS7 STREAMS Sockets* package is to provide *Sockets* capability for *STREAMS* in a similar manner as provided by *SVR 4.2* and later *Solaris* implementations. To accomplish this there are three (3) approaches that can be taken to implementing *Sockets* over *STREAMS*:

### 2.1 Socket Module

This approach implements the *SVR 4.2* `sockmod(4)` module and cooperating `libsocket(3)` library. The library and cooperating *STREAMS* module behave in a similar fashion to the `libxnet(3)` library and `timod(4)` module for XTI.

There are a set of input-output controls defined for sockets (explicitly for compatibility with *SVR 4.2*) that can be accepted by the `sockmod(4)` module. These input-output controls permit direct conversion between sockets function and kernel-space facilities.

The original `sockmod(4)` approach keep much of the socket state in user space in the fashion of `xti(3)`; however, this approach is just asking for trouble. Also, *Linux* also implements the *SVR 4.2* input-output controls for native Sockets and the resulting `libsocket(3)` library would then work for both *STREAMS*-based sockets and Linux native sockets.

Socket input-output controls defined for *SVR 4.2* are:

```
O_SL_GETUDATA
SL_SHUTDOWN
SL_LISTEN
SL_SETMYNAME
SL_SETPEERNAME
SL_GETINTRANSIT
SL_TCL_LINK
SL_TCL_UNLINK
SL_SOCKETPARAMS
SL_GETUDATA
```

### 2.2 Socket System

This approach implements the *SVR 4.2* `socksys(4)` driver. Opening *Streams* via the `socksys(4)` driver causes them to be transformed into native Sockets against which standard ‘libc’ socket system calls are sufficient. For compatibility with the `sockmod(4)` approach, the pushing the `sockmod(4)` module can be made to cause the same effect.

Before *Linux Fast-STREAMS* was developed, taking this approach was next to impossible due to the obfuscated nature and non-standard behaviour of the *LiS Stream head*. Now that *LiS* is completely deprecated, this approach is now possible.

*SVR 4.2* behaviour for the *Stream head* dictates that it respond to both `termio(7)` and `sockio(7)` input-output controls in addition to `streamio(7)` controls. That is, each *Stream head* can be a `fifo(4)`, a `pipe(4)`, a `tty(4)`, a `socket` or a `stream`. *LiS* never followed this behaviour: *Linux Fast-STREAMS* was built with it from the start.

Socket input-output controls recognized and intercepted by the *Linux Fast-STREAMS Stream head* are:

SIOCATMARK  
 SIOCGPGRP  
 SIOCSPGRP

Additional Sockets input-output controls are passed to the Stream as *TRANSPARENT* or *I\_STR(7)* input-output controls.

SIOCHIWAT	Set the high water mark.	<i>TRANSPARENT</i>
SIOGHIWAT	Get the high water mark.	<i>TRANSPARENT</i>
SIOCLOWAT	Set the low water mark.	<i>TRANSPARENT</i>
SIOGLOWAT	Get the low water mark.	<i>TRANSPARENT</i>
SIOCATMARK	Test whether at mark.	<i>Stream head</i>
SIOCGPGRP	Get process group.	<i>Stream head</i>
FIOCGPGRP		
SIOCSPGRP	Set process group.	<i>Stream head</i>
FIOCSPGRP		
FIONREAD TIOCINQ	Number of bytes to be read.	<i>I_STR(7)</i>
TIOOUTQ	Number of bytes to be sent.	<i>I_STR(7)</i>
FIONBIO	Set blocking i/o.	<i>TRANSPARENT</i>
SIOCPROTO	Set a new protocol entry.	<i>TRANSPARENT</i>
SIOCGETNAME	Get socket's name.	<i>TRANSPARENT</i>
SIOCGETPEER	Get socket's peer.	<i>TRANSPARENT</i>
SIOXPROTO	Clear protocol entry table.	<i>TRANSPARENT</i>
SIOC SOCKSYS	(See table below.)	<i>TRANSPARENT</i>

**Command**

**Library Call**

**System Call**

<i>SO_SOCKET</i>	<i>socket(3)</i>	—
<i>SO_ACCEPT</i>	<i>accept(3)</i>	<i>accept(2)</i>
<i>SO_BIND</i>	<i>bind(3)</i>	<i>bind(2)</i>
<i>SO_CONNECT</i>	<i>connect(3)</i>	<i>connect(2)</i>
<i>SO_GETPEERNAME</i>	<i>getpeername(3)</i>	<i>getpeername(2)</i>
<i>SO_GETSOCKNAME</i>	<i>getsockname(3)</i>	<i>getsockname(2)</i>
<i>SO_GETSOCKOPT</i>	<i>getsockopt(3)</i>	<i>getsockopt(2)</i>
<i>SO_LISTEN</i>	<i>listen(3)</i>	<i>listen(2)</i>
<i>SO_RECV</i>	<i>recv(3)</i>	<i>recv(2)</i>
<i>SO_RECVFROM</i>	<i>recvfrom(3)</i>	<i>recvfrom(2)</i>
<i>SO_SEND</i>	<i>send(3)</i>	<i>send(2)</i>
<i>SO_SENDTO</i>	<i>sendto(3)</i>	<i>sendto(2)</i>
<i>SO_SETSOCKOPT</i>	<i>setsockopt(3)</i>	<i>setsockopt(2)</i>
<i>SO_SHUTDOWN</i>	<i>shutdown(3)</i>	<i>shutdown(2)</i>
<i>SO_GETIPDOMAIN</i>	—	<i>getipdomain(2)</i>
<i>SO_SETIPDOMAIN</i>	—	<i>setipdomain(2)</i>
<i>SO_SETREUID</i>	—	<i>setreuid(2)</i>
<i>SO_SETREGID</i>	—	<i>getreuid(2)</i>
<i>SO_GETTIME</i>	—	<i>gettime(2)</i>
<i>SO_SETTIME</i>	—	<i>settime(2)</i>
<i>SO_GETITIMER</i>	—	<i>getitimer(2)</i>
<i>SO_SETITIMER</i>	—	<i>setitimer(2)</i>

<code>SO_SELECT</code>	–	<code>select(2)</code>
<code>SO_ADJTIME</code>	–	<code>adjtimex(2)</code>
<code>SO_RECVMSG</code>	<code>recvmsg(3)</code>	<code>recvmsg(2)</code>
<code>SO_SENDMSG</code>	<code>sendmsg(3)</code>	<code>sendmsg(2)</code>
<code>SO_SOCKETPAIR</code>	<code>socketpair(3)</code>	<code>socketpair(2)</code>

## 2.3 Socket Integration

With this approach, *Streams* that are usable for sockets are given the `IF_SOCK` attribute during registration. The *Stream head* is aware of this and creates a socket structure for each *Stream head* opened for the driver.

## 2.4 Solaris Approaches

The following is reprinted from an article in *UNIX<sup>®</sup> Insider* issue ‘3/9/01’ written by *Jim Mauro*.

Prior to *Solaris 2.6*, sockets were an abstraction that existed at the library level. That is, much of the socket state and socket semantics support were provided with the ‘`libsocket`’ library. The kernel’s view of a process’s socket connection entailed a file descriptor and linkage to a *Stream head*, which provided the path to the underlying transport. The disparity between the library socket state and the kernel’s view was one of several reasons a new implementation was introduced in *Solaris 2.6*.

To provide a relevant basis for comparison, we will start by looking at what happens in the pre-*Solaris 2.6* release (this is, releases up to and including *Solaris 2.5.1*) when a socket is created. The major software layers are shown in Figure XXX for reference.

The primary software components are the socket library and the `sockmod(4)` *STREAMS* module. The `specfs(5)` layer is shown for completeness and is part of the layering, due to the use of pseudo-devices as an entry point into the networking layers. To digress for a moment, the special file system, `specfs(5)` came out of *SVR 4 UNIX<sup>®</sup>* as a means of addressing the issue of *device special files* that exist on *UNIX<sup>®</sup>* on-disk file systems (e.g. *UFS*). *UNIX<sup>®</sup>* systems have always abstracted I/O (input/output) devices through device special files. The ‘`/dev`’ directory name space stores files that represent physical devices and pseudo-devices on the system. Using device major numbers, those device files provide an entry point into the appropriate device driver, and using minor numbers, they are able to uniquely identify one of potentially many devices of the same type. (That is something of an oversimplification, but it is sufficient for our purpose here in describing `specfs(5)`).

The ‘`/dev`’ directory resides on the ‘`root`’ file system, which is an instance of *UFS*. As such, references to the file system and its files and directories are handed using the *UFS* file system operations and *UFS* file operations. That is usually sufficient, but not desired behaviour for device special files. I/O to a device special file requires entry into a device driver. That is, issuing an `open(2)` system call on ‘`/dev/rmt/0`’ means someone wishes to open the tape device represented by ‘`/dev/rmt/0`’, thereby entering the appropriate driver’s

`xx_open()` routine. As a file on a *UFS* file system, the typical open routine called would be the `ufs_open()` code, but that is not what we want for devices. The ‘`specfs(5)`’ file system was designed to address such situations; it provides a straightforward mechanism for linking the underlying structures for file support in the kernel to the required device driver interfaces. Like all file systems in *Solaris* (and any *SVR4*-based *UNIX*<sup>®</sup>) it is based on the *VFS/vnode* infrastructure. (See *Solaris Internals* and *UNIX*<sup>®</sup> *Internals* in the Resources section for detailed information on *VFS*.)

Getting back to sockets in *Solaris 2.5.1*, the `specfs(5)` layer comes into play because the socket open ultimately results in an `open(2)` system call issued on the `tcp(4)` or `udp(4)` pseudo-device. More precisely, the socket library passes the arguments given to the `socket(3)` call to a lookup function that searches an internal (internal to ‘`libsocket.so`’) array to match the domain argument and retrieve a corresponding character string. It then uses the character string to find a match in the ‘`/etc/netconfig`’ file, which is used for transport selection and describes all the available transport protocols in *Solaris*. (See `netconfig(5)`.) This transport selection mechanism is an essential part of a network programming implementation; it allows for the interfaces to be protocol-independent, so the programmer is not required to maintain a different source base for Ethernet-based networks versus FDDI-based networks, etc.

A `netconfig(5)` data structure (defined in ‘`/usr/include/sys/netconfig.h`’) is populated based on the line entries in ‘`/etc/netconfig`’ that match the domain (as per the character string retrieved from the internal table), type, and protocol family specified in the `socket(3)` call. Among the `netconfig(5)` parameters, a device is defined that provides the entry point into the transport provider kernel module. For example, a call to ‘`socket(AF_INET, SOCK_STREAM, 0)`’ indicates an Internet transport that provides reliable, connection-oriented behaviour is desired. The *TCP* layer of the *TCP/IP* protocol family provides such a service, and the ‘`/etc/netconfig`’ entry defines ‘`/dev/tcp`’ as the device to open for entry into that transport layer. The socket library code will issue an `open(2)` on ‘`/dev/tcp`’ accordingly. If one were developing a network-based application using the *X/Open Transport Interface (XTI)* – a superset of what was the *Transport Layer Interface (TLI)* – the `t_open(3)` call would receive the ‘`/dev/tcp`’ argument explicitly for a connection using *TCP* as a transport protocol.

The block sitting below the `specfs(5)` in Figure XXX, the *Stream head*, is a generic part of a *STREAMS*-based communication path. The *Stream head* is created when a *STREAMS* device is opened. In Figure XXX, the `open(2)` to the ‘`/dev/tcp`’ transport layer, which is a *STREAMS* device, resulted in the creation of the *Stream head*. The *Stream head* translates the interface calls made by the socket library into *STREAMS* messages (the *STREAMS* framework is message-based and uses queues to move data downstream [from the user process to the *STREAMS* driver] and upstream [from the driver to the user process]). The *STREAMS* facility provides for the insertion (pushing) and removal (popping) of *STREAMS* modules in the data flow, between the *Stream*

*head* and the underlying driver. Each module implements a set of queues – a read queue and a write queue – for processing the data and messages. The generic picture is shown in Figure YYY.

In the context of *Solaris 2.5.1* sockets, the *STREAMS* module shown in Figure YYY is a kernel `sockmod(4)` module (located in the `/kernel/strmod` directory). `sockmod(4)` provides, in conjunction with `libsocket.so`, support for socket semantics using the *STREAMS* facility. That is, socket calls are handled initially by the socket library, then passed down to the *Stream head*, which transforms the calls into *STREAMS* messages and passes them down to `sockmod(4)`. Upstream messages are passed from the underlying device driver and transport provider through `sockmod(4)` and back up to the process. Thus, the functions contained in the `sockmod(4)` module include *STREAMS* queue reading and writing in the form of queue `read put` and `write put` code for moving data up and down the *Stream* as data is read and written from the socket. The `sockmod(4)` module communicates with the underlying transport using primitives and structures defines in the `/usr/include/sys/tihdr.h` header file.

The socket state maintained at the library level is in the form of a library-internal data structure, `_si_user`, which maintains various bits of information about the socket, and is what the internal socket create function returns on a socket call. Yes, it is the file descriptor that represents the socket that is returned to the user code `_si_user` is visible only to the library. You will find the structure definition for `_si_user` and associated structures that it links to (`si_uata` and `si_sockparams`) in `/usr/include/sys/sockmod.h`. If you look at the structure definition, you will see that the `_si_user` embeds the `si_uata` and `si_sockparams` structures, which maintain stat information (e.g. connected, bound), socket options (accept connection), information on the transport provider (e.g. service type), and family, type, and protocol used for the socket.

At the `sockmod(4)` layer, a socket is internally represented in the `so_so` data structure. Fields of interest there include an embedded `ti_info` structure (`/usr/include/sys/tiuser.h`) that manages transport provider information, a network buffer (`netbuf`) for data transfer, a `si_uata` structure that replicates the socket state (among other things), and message blocks (`mblk_t`), which are the basic unit of communication across *STREAMS*.

In *Solaris 2.6*, we did away with the `sockmod(4)` *STREAMS* module and trimmed a lot of code from `libsocket`. Most of the socket-related library interfaces result in system call traps into the kernel, without any library-level code executing. A few of the interfaces (`socket(3)` and `sockpair(3)`) execute some library-level code before entering the kernel. However, all the state information is maintained in the kernel, where it belongs. This creates a nice visibility feature – we can now see file descriptors that represent sockets.

```
sunsys> uname -a
SunOS sunsys 5.8 Generic_108528-01 sun4u sparc SUNW, Ultra-60
sunsys> srv &
[1]      7153
Socket port: # 34940
```

```

Send bug: 16384, Rcv buf: 24576

sunsys> pfiles 7153
7153:  srv
      Current rlimit: 1024 file descriptors
      0: S_IFCHR mode:0620 dev:32,0 ino:91176 uid:19822 gid:7 rdev:24,14
         O_RDWR|O_LARGEFILE
      1: S_IFCHR mode:0620 dev:32,0 ino:91176 uid:19822 gid:7 rdev:24,14
         O_RDWR|O_LARGEFILE
      2: S_IFCHR mode:0620 dev:32,0 ino:91176 uid:19822 gid:7 rdev:24,14
         O_RDWR|O_LARGEFILE
      3: S_IFSOCK mode:0666 dev:186,0 ino:63137 uid:0 gid:0 size:0
         O_RDWR
         sockname: AF_INET 0.0.0.0  port: 34940
sunsys>

```

In the above example, a simple *TCP* socket server process is started (`srv`, PID 7153). (The ‘Socket port’ and ‘Send buf’ lines are output from the `srv` process when it starts.) Using the `pfiles(1)` command to dump the process’s open file descriptors, we see that the file descriptor is identified as a socket, and we even get the socket type (`AF_INET`) and port number. (The freeware command, `lsf(1)`, is a great utility for extracting process file descriptor information if you are on an older *Sun OS* that does not have `pfiles(1)`. You can get `lsf(1)` from <ftp://vic.cc.purdue.edu/pub/tools/unix/lsf/>.)

The ‘`libsocket`’ changes associated with `sockfs(5)` maintain the documented interfaces. Both source and binary compatibility are maintained, as socket code compiled on early version of *Solaris* should work without recompilation on *Solaris 6* and later releases. Source code should move over and recompile with no changes as well.

The trimming down of the library-level socket code required providing a new means to map the domain type passed as an argument to `socket(3)` to facility lookup in ‘`/etc/netconfig`’. Recall that the *Solaris 2.5.1* socket library did this using an internal table. In *Solaris 6* and later, a new configuration file and command is introduced to provide that functionality. The ‘`/etc/sock2path`’ contains the necessary information to map the `socket(3)` call parameters to the appropriate transport provider and device. A new command, `soconfig(8)`, is used to maintain ‘`/etc/sock2path`’. It is executed automatically at boot time via an entry in the ‘`/etc/inittab`’ file. Reference the `sock2path(4)` and `soconfig(8)` manual pages for specifics. For most applications, the default entries in `sock2path(5)` are sufficient.

As a file system (pseudo-file system), `sockfs(5)` implements the generic *VFS/vnode* related support structures and exports the required file-system-specific functions. However, the entry into the `sockfs(5)`-specific functions does not necessarily follow the typical flow of a regular file open, which is vectored to the file-type-specific function through the use of macros and an operations table. That is, the issuing of an `open(2)` system call on a file enters a generic `vnode` code path and ultimately resolves through a `VOP_OPEN()` macro to the appropriate file-system-specific open code (e.g. `ufs_open` for a file an a *UFS* file system).



Sockets are created and opened using the `socket(3)` API. A call to `socket(3)` from user code enters the `libsocket` library, which handles the mapping to the transport provider device, then enters the `sockfs(5)` kernel module through an internal `so_create()` system call. The `sock_open()` (file system specific open routine) is invoked through the `so_create()` call, which is how other necessary create functions, such as an initialization function for the socket *Stream*, are called.

Other conventional system calls, such as `read(2)` or `write(2)` on a socket, are vectored into the `sockfs(5)` specific read and write code (`sock_read()` and `sock_write()`) through the standard *VFS/vnode* mechanism. Once entered, the `sockfs(5)` read/write code makes lower-level calls into the `sockfs(5)` subsystem designed to interface with the transport provider. For example, a `read(2)` system call on a socket vectors into `sock_read()`, which does some basic housekeeping and calls an internal `sorecvmsg()` (socket receive message) function. In `sorecvmsg()`, socket stat is tested and the request is moved downstream via a call to the *STREAMS* get-message function.

The most compelling part of the `sockfs(5)` implementation is that consolidation of all socket stat information is in a single structure, maintained in one place: the kernel. Sockets are represented internally as a `sonode`, defined in `‘/usr/include/sys/socketvar.h’`. All operations on a `sonode` take place within the kernel `sockfs(5)` subsystem, isolating state changes and eliminating the need to replicate state for consistency.





## 3 Reference

### 3.1 Files

*STRSOCK* creates the following kernel modules files in the kernel modules directory, `‘/lib/modules/2.4.20-28.7/’`:<sup>1</sup>

`‘modules.strsock’`

*STRSOCK* installs the following kernel module files in the kernel modules directory, `‘/lib/modules/2.4.20-28.7/strsock/’`:<sup>2</sup>

`‘streams_sockmod.ko’`

`‘streams_socksys.ko’`

*STRSOCK* installs the following header files in the system include directory, `‘/usr/include/strsock/’`:

`‘sys/strsock/config.h’`

`‘sys/strsock/version.h’`

`‘sys/sockio.h’`

`‘sys/sockmod.h’`

`‘sys/sockpath.h’`

`‘sys/socksys.h’`

`‘sys/socklib.h’`

`‘sockdb.h’`

`‘sockio.h’`

`‘sockmod.h’`

`‘socksys.h’`

*STRSOCK* installs the following test programs in the system libexec directory, `‘/usr/libexec/strsock/’`:<sup>3</sup>

`‘send-pr’`

`‘send-pr.config’`

The `send-pr` stand-alone shell script can be used for the automatic generation of problem reports for the *OpenSS7 STREAMS Sockets* package. The `‘send-pr.config’` file provides localized definitions used by the `send-pr` program. For more information on problem reports, See [Section 7.2 \[Problem Reports\]](#), page 93, and, in particular, See [Section 7.2.4 \[Stand Alone Problem Reports\]](#), page 96.

`‘test-sockpath’`

test case executable.

`‘test-socket’`

test case executable.

`‘test-socklib’`

test case executable.

<sup>1</sup> The kernel version ‘2.4.20-28.7’ is just an example. For the running kernel, `‘uname -r’` is expected.

<sup>2</sup> The kernel version ‘2.4.20-28.7’ is just an example. For the running kernel, `‘uname -r’` is expected.

<sup>3</sup> Note that on some systems, `‘/usr/libexec’` does not exist, and `‘/usr/lib’` is used instead.

`'test-sockmod'`  
test case executable.

`'test-socksys'`  
test case executable.

`'testsuite'`

`'atlocal'` The `testsuite` stand-alone shell script invokes test cases in the test programs above as compiled into a comprehensive regression, troubleshooting and validation test suite for the *OpenSS7 STREAMS Sockets* drivers. The `'atlocal'` file provides localized definitions used by the `testsuite` program. For more information on test suites, See [Section 7.1 \[Test Suites\]](#), page 89, and, in particular, See [Section 7.1.2.1 \[Running Test Suites\]](#), page 93.

*STRSOCK* installs the following utility programs in the system binary directory, `'/usr/sbin/`:

`'initsock'`

`'soconfig'`

`'strsock_mknod'`

This utility can be used by init scripts or administrative users to create or remove device nodes in the `'/dev'` directory for *OpenSS7 STREAMS Sockets* drivers.

*STRSOCK* installs the following static and shared object libraries in the system library directory, `'/usr/lib/` (32-bit libraries) and `'/usr/lib64/` (64-bit libraries):

`'libsockpath.so.0.0.0'`

`'libsockpath.so.0'`

`'libsockpath.so'`

`'libsockpath.a'`

`'libsockpath.la'`

`'libsocket.a'`

`'libsocket.la'`

`'libsocklib.a'`

`'libsocklib.la'`

*STRSOCK* installs the following init scripts in the system init directory, `'/etc/rc.d/init.d/` (non-Debian) or `'/etc/init.d/` (Debian):

`'strsock'` This is the name of the system init script on non-Debian based systems.

`'strsock.sh'`

This is the name of the system init script on Debian based systems.

*STRSOCK* installs the following system configuration files in the configuration directory, `'/etc/`:

`'strsock.conf'`

This file provided configuration information for any system controls affected by the `'strsock'` package.

`'modutils/strsock'`

This file provides module definitions and demand loading aliases for the `'strsock'` package. This file is really only applicable to older 2.4 kernels.

‘sock2path’

This file provides the `sock2path(5)` definitions for the *OpenSS7 STREAMS Sockets* drivers. `sock2path(5)` definitions are used by the ‘strsock’ package and the ‘libsocket’ library.

*STRSOCK* installs the following system configuration file in the system configuration directory, ‘/etc/sysconfig/’ (non-Debian) or ‘/etc/default/’ (Debian):

‘strsock’ This file provides system configuration information used by init scripts for the ‘strsock’ package. Some options of init script execution can be controlled by this file.

*STRSOCK* installs the following info files in the system info directory, ‘/usr/share/info/’:

‘strsock.info’

‘strsock.info-1’

‘strsock.info-2’

These files contain this manual in *GNU info* format.

*STRSOCK* installs the following manual page macros and reference database files in the system man directory, ‘/usr/share/man/’:<sup>4</sup>

‘strsock.macros’

This file contains manual page macro definitions included by the manual pages included in the package.

‘strsock.refs’

This file contains a reference database referenced by the manual pages included in the package.

*STRSOCK* installs the following manual pages in the system man directory, ‘/usr/share/man/man3/’:

‘accept.3’

‘bind.3’

‘connect.3’

‘getpeername.3’

‘getsockname.3’

‘getsockopt.3’

‘libsocket.3’

‘listen.3’

‘recv.3’

‘recvfrom.3’

‘recvmsg.3’

‘send.3’

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<sup>4</sup> Note that macro and reference database files are not installed if the package is configured for cooked manpages.

'sendmsg.3'  
 'sendto.3'  
 'setsockopt.3'  
 'shutdown.3'  
 'socket.3'  
 'socketpair.3'  
 'sockets.3'  
 'endsockpath.3'  
 'freesockpathent.3'  
 'getsockpath.3'  
 'getsockpathent.3'  
 'setsockpath.3'  
 'sockpath.3'  
 'sp\_perror.3'  
 'sp\_sperror.3'  
 'libsocklib.3'  
 'socklib.3'

*STRSOCK* installs the following manual pages in the system man directory, `‘/usr/share/man/man4/’`:

'sockmod.4'  
 'socksys.4'

*STRSOCK* installs the following manual pages in the system man directory, `‘/usr/share/man/man5/’`:

'strsock.5'  
     manual page for the `strsock(5)` package.

'sock2path.5'

*STRSOCK* installs the following manual pages in the system man directory, `‘/usr/share/man/man8/’`:

'strsock\_mknod.8'  
     Documentation for the `strsock_mknod(8)` utility program.

'initsock.8'  
 'soconfig.8'  
 'test-socket.8'  
 'test-socklib.8'  
 'test-sockmod.8'  
 'test-sockpath.8'  
 'test-socksys.8'

## 3.2 Drivers

## 3.3 Modules

## 3.4 Libraries

### **3.5 Utilities**

### **3.6 Development**



## 4 Conformance





## 5 Releases

This is the OpenSS7 Release of the OpenSS7 STREAMS Sockets tools, drivers and modules used with the *Linux Fast-STREAMS* or *Linux STREAMS*<sup>1</sup> SVR 4.2 STREAMS releases.

The purpose of providing a separate release of this package was to separate the OpenSS7 STREAMS Sockets tools, headers, drivers and modules from the *Linux STREAMS*<sup>2</sup> package for use with both *Linux STREAMS*<sup>3</sup> and *Linux Fast-STREAMS* in preparation for replacement of the former by the later.

The following sections provide information on OpenSS7 STREAMS Sockets releases as well as compatibility information of OpenSS7 release to mainstream UNIX releases of the core, modules and drivers, as well as Linux kernel compatibility.

### 5.1 Prerequisites

The quickest and easiest way to ensure that all prerequisites are met is to download and install this package from within the *OpenSS7 Master Package*, `openss7-0.9.2.G`, instead of separately.

Prerequisites for the OpenSS7 STREAMS Sockets package are as follows:

1. *Linux* distribution, somewhat *Linux Standards Base* compliant, with a 2.4 or 2.6 kernel and the appropriate tool chain for compiling out-of-tree kernel modules. Most recent *Linux* distributions are usable out of the box, but some development packages must be installed. For more information, see [Section 5.2 \[Compatibility\]](#), page 34.
  - A fairly LSB compliant GNU/Linux distribution.<sup>4</sup>
  - Linux 2.4 kernel (2.4.10 - 2.4.27), or
  - Linux 2.6 kernel (2.6.3 - 2.6.26);
  - glibc2 or better.
  - GNU groff (for man pages).<sup>5</sup>
  - GNU texinfo (for info files).

(Note: If you acquired `strsock` a part of the *OpenSS7 Master Package*, then the dependencies listed below will already have been met by unpacking the master package.)

2. *OpenSS7 Linux Fast-STREAMS*, `streams-0.9.2.4`.<sup>6</sup>
3. *OpenSS7 STREAMS Compatibility Modules*, `strcompat-0.9.2.7`.
4. *OpenSS7 STREAMS XNS*, `strxns-0.9.2.7`.
5. *OpenSS7 STREAMS XTI/TLI*, `strxnet-0.9.2.12`.

If you need to rebuild the package from sources with modifications, you will need a larger GNU tool chain as described in See [Section 6.2.8 \[Downloading from CVS\]](#), page 55.

<sup>1</sup> *Linux STREAMS* is buggy, unsupported and deprecated. Do not use it.

<sup>2</sup> *Linux STREAMS* is buggy, unsupported and deprecated. Do not use it.

<sup>3</sup> *Linux STREAMS* is buggy, unsupported and deprecated. Do not use it.

<sup>4</sup> See [Section 5.2.1 \[GNU/Linux Distributions\]](#), page 34, for more information.

<sup>5</sup> If you are using a Debian release, please make sure to install the groff extension package (`'groff_ext'`), as it contains the `refer` or `grefer` commands necessary for including references in the manual pages.

<sup>6</sup> Although, at one time, this package supported *LiS*, *LiS* is now deprecated and unsupported.

## 5.2 Compatibility

This section discusses compatibility with major prerequisites.

### 5.2.1 GNU/Linux Distributions

*OpenSS7 STREAMS Sockets* is compatible with the following *Linux* distributions:<sup>7</sup>

- CentOS Enterprise Linux 3.4 (centos34) TBD
- CentOS Enterprise Linux 4.0 (centos4) TBD
- CentOS Enterprise Linux 4.92 (centos49) TBD
- CentOS Enterprise Linux 5.0 (centos5)
- CentOS Enterprise Linux 5.1 (centos51)
- CentOS Enterprise Linux 5.2 (centos52)
- Debian 3.0r2 Woody (deb3.0) TBD
- Debian 3.1r0a Sarge (deb3.1) TBD
- Debian 4.0r1 Etch (deb4.0)
- Debian 4.0r2 Etch (deb4.0)
- Debian 4.0r3 Etch (deb4.0)
- Fedora Core 1 (FC1) TBD
- Fedora Core 2 (FC2) TBD
- Fedora Core 3 (FC3) TBD
- Fedora Core 4 (FC4) TBD
- Fedora Core 5 (FC5) TBD
- Fedora Core 6 (FC6) TBD
- Fedora 7 (FC7)
- Fedora 8 (FC8)
- Fedora 9 (FC9)
- Gentoo 2006.1 (untested) TBD
- Gentoo 2007.1 (untested) TBD
- Lineox 4.026 (LEL4) TBD
- Lineox 4.053 (LEL4) TBD
- Mandrakelinux 9.2 (MDK92) TBD
- Mandrakelinux 10.0 (MDK100) TBD
- Mandrakelinux 10.1 (MDK101) TBD
- Mandriva Linux LE2005 (MDK102) TBD
- Mandriva Linux LE2006 (MDK103) TBD
- Mandriva One (untested)
- RedHat Linux 7.2 (RH7)
- RedHat Linux 7.3 (RH7)

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<sup>7</sup> Items marked as 'TBD' are scheduled to have support deprecated. That is, in a future release, the distributions marked 'TBD' will not longer be validated before release.

- RedHat Linux 8.0 (RH8) TBD
- RedHat Linux 9 (RH9) TBD
- RedHat Enterprise Linux 3.0 (EL3) TBD
- RedHat Enterprise Linux 4 (EL4)
- RedHat Enterprise Linux 5 (EL5)
- SuSE 8.0 Professional (SuSE8.0) TBD
- SuSE 9.1 Personal (SuSE9.1) TBD
- SuSE 9.2 Professional (SuSE9.2) TBD
- SuSE OpenSuSE (SuSEOSS) TBD
- SuSE 10.0 (SuSE10.0) TBD
- SuSE 10.1 (SuSE10.1) TBD
- SuSE 10.2 (SuSE10.2) TBD
- SuSE 10.3 (SuSE10.3) TBD
- SuSE 11.0 (SuSE11.0)
- SLES 9 (SLES9) TBD
- SLES 9 SP2 (SLES9) TBD
- SLES 9 SP3 (SLES9) TBD
- SLES 10 (SLES10)
- Ubuntu 5.10 (ubu5.10) TBD
- Ubuntu 6.03 LTS (ubu6.03) TBD
- Ubuntu 6.10 (ubu6.10) TBD
- Ubuntu 7.04 (ubu7.04) TBD
- Ubuntu 7.10 (ubu7.10)
- Ubuntu 8.04 (ubu8.04)
- WhiteBox Enterprise Linux 3.0 (WBEL3) TBD
- WhiteBox Enterprise Linux 4 (WBEL4) TBD

When installing from the tarball (see [Section 6.5.3 \[Installing the Tar Ball\], page 76](#)), this distribution is probably compatible with a much broader array of distributions than those listed above. These are the distributions against which the current maintainer creates and tests builds.

## 5.2.2 Kernel

The *OpenSS7 STREAMS Sockets* package compiles as a *Linux* kernel module. It is not necessary to patch the *Linux* kernel to build or use the package.<sup>8</sup> Nor do you have to recompile your kernel to build or use the package. OpenSS7 packages use `autoconf` scripts to adapt the package source to your existing kernel. The package builds and runs nicely against production kernels from the distributions listed above. Rather than relying on kernel versions, the `autoconf` scripts interrogate the kernel for specific features and variants to

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<sup>8</sup> At a later date, it is possible to move this package into the kernel, however, with continued resistance to STREAMS from within the *Linux* developer community, this is currently unlikely.

better adapt to distribution production kernels that have had patches applied over the official [kernel.org](http://kernel.org) sources.

The *OpenSS7 STREAMS Sockets* package is compatible with 2.4 kernel series after 2.4.10 and has been tested up to and including 2.4.27. It has been tested from 2.6.3 up to and including 2.6.26 (with Fedora 9, openSUSE 11.0 and Ubuntu 8.04 patchsets). Please note that your mileage may vary if you use a kernel more recent than 2.6.26.4: it is difficult to anticipate changes that kernel developers will make in the future. Many kernels in the 2.6 series now vary widely by release version and if you encounter problems, try a kernel within the supported series.

UP validation testing for kernels is performed on all supported architectures. SMP validation testing was initially performed on UP machines, as well as on an Intel 3.0GHz Pentium IV 630 with HyperThreading enabled (2x). Because HyperThreading is not as independent as multiple CPUs, SMP validation testing was limited. Current releases have been tested on dual 1.8GHz Xeon HP servers (2x) as well as dual quad-core SunFire (8x) servers.

It should be noted that, while the packages will configure, build and install against XEN kernels, that problems running validation test suites against XEN kernels has been reported. *XEN kernels are explicitly not supported.* This may change at some point in the future if someone really requires running OpenSS7 under a XEN kernel.

### 5.2.3 Architectures

The *OpenSS7 STREAMS Sockets* package compiles and installs on a wide range of architectures. Although it is believed that the package will work on all architectures supported by the Linux kernel being used, validation testing has only been performed with the following architectures:

- ix86
- x86\_64
- ppc (MPC 860)
- ppc64

32-bit compatibility validation testing is performed on all 64-bit architectures supporting 32-bit compatibility. If you would like to validate an OpenSS7 package on a specific machine architecture, you are welcome to sponsor the project with a test machine.

### 5.2.4 Linux STREAMS

The *OpenSS7 STREAMS Sockets* package is currently compatible with *Linux STREAMS*,<sup>9</sup> however, to use the *OpenSS7 STREAMS Sockets* package with *LiS* requires use of the OpenSS7 release packages of *LiS*. The *OpenSS7 STREAMS Sockets* package is compatible with the OpenSS7 **LiS-2.18.7** release that is available from the [The OpenSS7 Project Downloads Page](#). But, do not use *LiS*: it is buggy, unsupported and deprecated. Use *Linux Fast-STREAMS* instead.

### 5.2.5 Linux Fast-STREAMS

The *OpenSS7 STREAMS Sockets* package is currently compatible with *Linux Fast-STREAMS (LFS)*. The *OpenSS7 STREAMS Sockets* package is compatible with

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<sup>9</sup> *Linux STREAMS* is buggy, unsupported and deprecated. Do not use it.

the OpenSS7 **streams-0.9.2.4** release that is available from the [The OpenSS7 Project Downloads Page](#).

## 5.3 Release Notes

The sections that follow provide information on OpenSS7 releases of the *OpenSS7 STREAMS Sockets* package.

### Major changes for release **strsock-0.9.2.4**

This is the fourth separate *OpenSS7 Project* release of the *OpenSS7 STREAMS Sockets* package whose components were formerly part of the ‘strss7’, ‘strxnet’ and ‘streams’ packages. These networking modules provide the Sockets library. The package contains all the necessary manual pages and other documentation. The package is packaged as an OpenSS7 style autoconf tarball.

This is the fourth alpha release and is part of the OpenSS7 Master Package (‘**openss7-0.9.2.G**’). The release includes maintenance support for recent distributions and tool chain, but also includes some performance and feature upgrades and inspection bug fixes. It deprecates previous releases. Please upgrade before reporting bugs on previous releases.

Major features since the last public release are as follows:

- Minor documentation corrections.
- Kernel module license made explicit "GPL v2". And then changed back to "GPL".
- License upgrade to *AGPL Version 3*.
- Support for flex 2.5.33 in maintainer mode.
- Ability to strap out major documentation build and installation primarily for embedded targets.
- Improvements to common build process for embedded and cross-compile targets.
- Updated tool chain to ‘m4-1.4.12’, ‘autoconf-2.63’ and ‘texinfo-4.13’.
- Conversion of RPM spec files to common approach for major subpackages.
- Updated references database for manual pages and roff documents.
- Build system now builds **yum(8)** repositories for RPMs and **apt-get(8)** repositories for DEBs. Installation documentation has been updated to include details of repository install sourcesref.
- Added **MODULE\_VERSION** to all modules and drivers.
- Several important bug fixes for thread safety of the socket library: see ‘**BUGS**’ in the release for more information.

*This is a public alpha release of the package: it deprecates previous releases. Please upgrade to the current release before reporting bugs. Please see ‘**README-alpha**’ in the release, or [Section 5.4 \[Maturity\]](#), page 39.*

As with other OpenSS7 releases, this release configures, compiles, installs and builds RPMs and DEBs for a wide range of Linux 2.4 and 2.6 RPM- and DPKG-based distributions, and can be used on production kernels without patching or recompiling the kernel.

This package is publicly released under the *GNU Affero General Public License Version 3*. The release is available as an autoconf tarball, SRPM, DSC, and set of binary RPMs and

DEBs. See the [downloads page](#) for the `autoconf` tarballs, SRPMs and DSCs. For tarballs, SRPMs, DSCs and binary RPMs and DEBs, see the [strsock package page](#).

See <http://www.openss7.org/codefiles/strsock-0.9.2.4/ChangeLog> and <http://www.openss7.org/codefiles/strsock-0.9.2.4/NEWS> in the release for more information. Also, see the ‘`strsock.pdf`’ manual in the release (also in html [http://www.openss7.org/strsock\\_manual.html](http://www.openss7.org/strsock_manual.html)).

For the news release, see [http://www.openss7.org/rel20081029\\_C.html](http://www.openss7.org/rel20081029_C.html).

### Major changes for release `strsock-0.9.2.3`

This *OpenSS7 Project* release is the third separate release of the *OpenSS7 STREAMS Sockets* package whose components were formerly part of the ‘`strss7`’, ‘`strxnet`’ and ‘`streams`’ packages. These networking modules provide the Sockets library. The package contains all the necessary manual pages and other documentation. The package is packaged as an OpenSS7 style `autoconf` tarball.

This is the third alpha release and is part of the OpenSS7 Master Package (‘`openss7-0.9.2.F`’). This release is primarily a maintenance release supporting recent distributions and tool chains.

Major features since the last public release are as follows:

- Support build on openSUSE 10.2.
- Support build on Fedora 7 with 2.6.21 kernel.
- Support build on CentOS 5.0 (RHEL5).
- Support build on Ubuntu 7.04.
- Updated to `gettext` 0.16.1.
- Changes to support build on 2.6.20-1.2307.fc5 and 2.6.20-1.2933.fc6 kernel.
- Supports build on Fedora Core 6.
- Support for recent distributions and tool chains.

### Major changes for release `strsock-0.9.2.2`

This *OpenSS7 Project* release is the second separate release of the *OpenSS7 STREAMS Sockets* package whose components were formerly part of the ‘`strss7`’, ‘`strxnet`’ and ‘`streams`’ packages. These networking modules provide the Sockets library. The package contains all the necessary manual pages and other documentation. The package is packaged as an OpenSS7 style `autoconf` tarball.

This is the second alpha release for *Linux Fast-STREAMS* and is part of the OpenSS7 Master Package (‘`openss7-0.9.2.E`’). This release is primarily a maintenance release supporting recent distributions and tool chains.

Major features since the last public release are as follows:

- Improvements to the common build environment with better support for standalone package builds on 2.4 kernels.
- Support for `autoconf` 2.61, `automake` 1.10 and `gettext` 0.16.
- Support for Ubuntu 6.10 distribution and bug fixes for i386 kenels.
- The package now looks for other subpackages with a version number as unpacked by separate tarball.

## Major changes for release `strsock-0.9.2.1`

This *OpenSS7 Project* release is the first separate release of the *OpenSS7 STREAMS Sockets* package whose components were formerly part of the ‘`strss7`’, ‘`strxnet`’ and ‘`streams`’ packages. These networking modules provide the Sockets library. The package contains all the necessary manual pages and other documentation. The package is packaged as an OpenSS7 style autoconf tarball.

This is the initial alpha release for *Linux Fast-STREAMS* and is part of the OpenSS7 Master Package (‘`openss7-0.9.2.D`’).

This release is the initial public release.

- Support for most recent 2.6.18 kernels (including Fedora Core 5 with inode diet patch-set).

## 5.4 Maturity

The *OpenSS7 Project* adheres to the following release philosophy:

- pre-alpha release
- alpha release
- beta release
- gamma release
- production release
- unstable release

### 5.4.1 Pre-Alpha Releases

*Pre-alpha* releases are releases that have received no testing whatsoever. Code in the release is not even known to configure or compile. The purpose of a pre-alpha release is to make code and documentation available for inspection only, and to solicit comments on the design approach or other characteristics of the software package.

*Pre-alpha* release packages ship containing warnings recommending that the user not even execute the contained code.

### 5.4.2 Alpha Releases

*Alpha* releases are releases that have received little to no testing, or that have been tested and contains known bugs or defects that make the package unsuitable even for testing. The purpose for an *alpha* release are the same as for the pre-alpha release, with the additional purpose that it is an early release of partially functional code that has problems that an external developer might be willing to fix themselves and contribute back to the project.

*Alpha* release packages ship containing warnings that executing the code can crash machines and might possibly do damage to systems upon which it is executed.

### 5.4.3 Beta Releases

*Beta* releases are releases that have received some testing, but the testing to date is not exhaustive. *Beta* release packages do not ship with known defects. All known defects are resolved before distribution; however, as exhaustive testing has not been performed,



unknown defects may exist. The purpose for a *beta* release is to provide a baseline for other organizations to participate in the rigorous testing of the package.

*Beta* release packages ship containing warnings that the package has not been exhaustively tested and that the package may cause systems to crash. Suitability of software in this category for production use is not advised by the project; however, as always, is at the discretion of the user of the software.

#### 5.4.4 Gamma Releases

*Gamma* releases are releases that have received exhaustive testing within the project, but external testing has been minimal. *Gamma* release packages do not ship with known defects. As exhaustive internal testing has been performed, unknown defects should be few. Please remember that there is NO WARRANTY on public release packages.

*Gamma* release packages typically resolve problems in previous *beta* releases, and might not have had full regression testing performed. Suitability of software in this category for production use is at the discretion of the user of the software. *The OpenSS7 Project* recommends that the complete validation test suites provided with the package be performed and pass on target systems before considering production use.

#### 5.4.5 Production Releases

*Production* releases are releases that have received exhaustive testing within the project and validated on specific distributions and architectures. *Production* release packages do not ship with known defects. Please remember that there is NO WARRANTY on public release packages.

*Production* packages ship containing a list of validated distributions and architectures. Full regression testing of any maintenance changes is performed. Suitability of software in this category for production use on the specified target distributions and architectures is at the discretion of the user. It should not be necessary to preform validation tests on the set of supported target systems before considering production use.

#### 5.4.6 Unstable Releases

*Unstable* releases are releases that have received extensive testing within the project and validated on a a wide range of distributions and architectures; however, is has tested unstable and found to be suffering from critical problems and issues that cannot be resolved. Maintenance of the package has proved impossible. *Unstable* release packages ship with known defects (and loud warnings). Suitability of software in this category for production use is at the discretion of the user of the software. *The OpenSS7 Project* recommends that the problems and issues be closely examined before this software is used even in a non-production environment. Each failing test scenario should be completely avoided by the application. *OpenSS7* beta software is more stable that software in this category.

### 5.5 Bugs

#### 5.5.1 Defect Notices

*OpenSS7 STREAMS Sockets* has unknown defects. This is an *alpha* release. Some defects could be harmful. No validation testing whatsoever has been performed by the *OpenSS7*



*Project* on this software. The software might fail to configure or compile on some systems. The *OpenSS7 Project* recommends that you **do not use this software for purposes other than development or evaluation, and then only with great care**. Use at your own risk. Remember that there is **NO WARRANTY**.<sup>10</sup>

**This software is *alpha* software. As such, it can likely crash your kernel. Installation of the software can irreparably mangle your header files or Linux distribution in such a way as to make it unusable. Crashes could lock your system and rebooting the system might not repair the problem. You can possibly lose all the data on your system. Because this software can crash your kernel, the resulting unstable system could destroy computer hardware or peripherals making them unusable. You could void the warranty on any system on which you run this software. YOU HAVE BEEN WARNED.**

### 5.5.2 Known Defects

With the exception of packages not originally created by the *OpenSS7 Project*, the *OpenSS7 Project* software does not ship with known bugs in any release stage except *pre-alpha*. *OpenSS7 STREAMS Sockets* had no known bugs at the time of release.

### 5.5.3 Defect History

This section contains historical bugs that were encountered during development and their resolutions. This list serves two purposes:

1. It captures bugs encountered between releases during development that could possibly reoccur (and the Moon is made of blue cheese). It therefore provides a place for users to look if they encounter a problem.
2. It provides a low overhead bug list between releases for developers to use as a ‘TODO’ list.

### Bugs

001. 2008-08-17T03:42:23+0000

The socket, socklib and sockpath libraries were discovered to contain a thread-safety bug caused by newer behaviour of `pthread_once()` causing the libraries to core dump when used on recent implementations of pthreads (nptl).

*\*fixed\** in `strsock-0.9.2.4`.

## 5.6 Schedule

### Current Plan

This package is still incomplete. It is missing a fully functional Stream head socket library, module or driver implementation. Also, performance testing of STREAMS INET drivers indicates that STREAMS-based networking components could exhibit far superior performance to that exhibited by legacy Linux sockets. To accomplish this requires fully implementing `socklib(3)`, `sockmod(4)` module or `socksys(4)` driver, creating validation test suites, and performance analysis and comparison with legacy Linux mechanisms.

<sup>10</sup> See sections **Disclaimer of Warranty** and **Limitation of Liability** under [\[GNU Affero General Public License\]](#), page 102.

This package is not currently a priority for the OpenSS7 project, which is focussed on more telecom-specific protocol stacks and capabilities. Nevertheless, if completion of this package is important to your industry and your organization is able to fund further development or contribute the missing items, contact us on the openss7-develop mailing list. Until funding or a mandate surfaces, this package will likely continue as a proof-of-concept only. It will be maintained in a compilable and installable package (that is, it will be updated for current Linux distributions and kernels) on the same basis as other packages in the OpenSS7 master package.

## Things to Do

- Testing. This package is completely untested.  
*\*todo\**
- Create a **socksys(4)** *Socket System STREAMS* driver.  
*\*todo\**
- It would be interesting to perform some *Netperf* and *Iperf* performance tests against *STREAMS*-based network drivers supporting *Transport Provider Interface (TPI)* and *Sockets* using this socket system. Without **sockmod(4)** and ‘**libsocket**’ it was only possible to use *Netperf* for performance testing, and then only using the XTI tests.  
*\*todo\**
- Create the **socket(3)** ‘**libsocket**’ shared library.  
*\*todo\**
- Create a **sockmod(4)** *Socket Module STREAMS* module.  
*\*todo\**
- Move already written code from the ‘**stacks**’ or ‘**strss7**’ directories into the ‘**src**’ directory.  
*\*todo\**
- Create a skeleton directory and manual and place **strsock** as a sub-package in the *OpenSS7 Master Package*.  
*\*done\**

You are reading it.

The **strsock** package is currently incomplete.

The purpose of the package was to move *STREAMS* socket capabilities outside of the *STREAMS* release package so as to allow them to be used with both *LiS* and *Linux Fast-STREAMS*. As *Linux Fast-STREAMS* has already shown superior to *LiS* in terms of both performance and conformance, it is no longer necessary to keep these packages separate and they can be combined once again (or still) with *Linux Fast-STREAMS*.

## 5.7 History

For the latest developments with regard to history of changes, please see the ‘**ChangeLog**’ file in the release package.

## 6 Installation

### 6.1 Repositories

The OpenSS7 STREAMS Sockets package release can be accessed from the repositories of [The OpenSS7 Project](#). For `rpm(1)` based systems, the package is available in a `yum(8)` repository based on ‘`repomd`’ XML and may also be accessed using `zypper(8)` or `yast(8)`. For `dpkg(1)` based systems, the package is available in a `apt(8)` repository.

By far the easiest (most repeatable and manageable) form for installing and using *OpenSS7* packages is to install packages from the `yum(8)` or `apt(8)` repositories. If your distribution does not support `yum(8)`, `zypper(8)`, `yast(8)` or `apt(8)`, then it is still possible to install the RPMs or DEBs from the repositories using `rpm(1)`, `dpkg(1)`; or by using `wget(1)` and then installing them from RPM or DEB using `rpm(1)` or `dpkg(1)` locally.

If binaries are not available for your distribution or specific kernel, but your distribution supports `rpm(1)` or `dpkg(1)`, the next best method for installing and using *OpenSS7* packages is to download and rebuild the source RPMs or DSCs from the repository. This can also be performed with `yum(8)`, `zypper(8)`, `yast(8)`, `apt(8)`; or directly using `wget(1)`, `rpm(1)` or `dpkg(1)`.

If your architecture does not support `rpm(1)` or `dpkg(1)` at all, or you have special needs (such as cross-compiling for embedded targets), the final resort method is to download, configure, build and install from tarball. In this later case, the easiest way to build and install *OpenSS7* packages from tarball is to use the tarball for the *OpenSS7 Master Package*, `openss7-0.9.2.G`.

#### 6.1.1 Repositories for YUM

To install or upgrade from the *OpenSS7* ‘`repomd`’ repositories, you will need a file in your ‘`/etc/yum.repo.d/`’ directory. This file can be obtained directly from the *OpenSS7 repository*, like so:

```
$> REPOS="http://www.openss7.org/repos/rpms"
$> wget $REPOS/centos/5.2/x86_64/repodata/openss7.repo
$> sudo cp -f openss7.repo /etc/yum.repo.d/
$> sudo yum makecache
```

This example assumes the the distribution is ‘`centos`’ and the distribution release is ‘`5.2`’ and the architecture requires is ‘`x86_64`’. Another example would be ‘`$REPOS/i686/suse/11.0/i686/repodata/openss7.repo`’, for using `yum(8)` with SUSE.

Once the repository is set up, *OpenSS7* includes a number of virtual package definitions that eas the installation and removal of kernel modules, libraries and utilities. Downloading, configuring, building and installation for a single-kernel distribution is as easy as:

```
$> sudo yum install strsock
```

Removing the package is as easy as:

```
$> sudo yum remove strsock
```

If you have difficulty downloading the ‘`openss7.repo`’ file, edit the following information into the file and place it into the ‘`/etc/yum.repo.d/openss7.repo`’ file:

```

-| [openss7]
-| enabled = 1
-| name = OpenSS7 Repository
-| baseurl = http://www.openss7.org/repos/rpms/centos/5.2/x86_64
-| gpgcheck = 1
-| gpgkey = http://www.openss7.org/pubkey.asc

```

Note that it is also possible to point to these repositories as an additional installation source when installing CentOS, RedHat, Fedora, or others. You will have an additional *STREAMS* category from which to choose installation packages.

Some additional installation real or virtual package names and the installations they accomplish are as follows:

`'strsock'`

This package can be used to install or remove the entire OpenSS7 STREAMS Sockets package. When installing, kernel modules will be installed automatically for the highest version kernel on your system. When removing, all corresponding kernel modules will also be removed.

`'strsock-devel'`

This package can be used to install or remove the development components of the OpenSS7 STREAMS Sockets package. When installing, `'strsock'` and appropriate kernel module and kernel module development and debug packages will also be installed. When removing, the development package and all kernel module development and debug packages will also be removed.

`'strsock-2.4.20-28.7'`

This package can be used to install or remove the package for a specific kernel version. When installing, the `'strsock'` package will also be installed if necessary. When removing the last kernel module package, the `'strsock'` package will also be removed.

Note that the version `'2.4.20-28.7'` is just an example. Use the version returned by `'$(uname -r)'` for the kernel for which you wish to install or remove the packages.

`'strsock-2.4.20-28.7-devel'`

This package can be used to install or remove the development and debug packages for a specific kernel version. When installing, the `'strsock'` and `'strsock-devel'` packages will also be installed if necessary. When removing the development and debug for kernel modules for the last kernel, the `'strsock-devel'` package will also be removed.

Note that the version `'2.4.20-28.7'` is just an example. Use the version returned by `'$(uname -r)'` for the kernel for which you wish to install or remove the packages.

For assistance with specific RPMs, see [Section 6.2.3 \[Downloading the Binary RPM\]](#), page 47.

### 6.1.2 Repositories for APT

For assistance with specific DEBs, see [Section 6.2.4 \[Downloading the Debian DEB\]](#), page 50.

## 6.2 Downloading

The OpenSS7 STREAMS Sockets package releases can be downloaded from the downloads page of [The OpenSS7 Project](#). The package is available as a binary RPM (for popular architectures) a source RPM, Debian binary DEB and source DSC, or as a tar ball. If you are using a browsable viewer, you can obtain the OpenSS7 release of `strsock` from the links in the sections that follow.

By far the easiest (most repeatable and manageable) form for installing and using *OpenSS7* packages is to download and install individual packages from binary RPM or DEB. If binary RPMs or DEBs are not available for your distribution, but your distribution supports `rpm(1)` or `dpkg(1)`, the next best method for installing and using *OpenSS7* packages is to download and rebuild the source RPMs or DSCs.

If your architecture does not support `rpm(1)` or `dpkg(1)` at all, or you have special needs (such as cross-compiling for embedded targets), the final resort method is to download, configure, build and install from tarball. In this later case, the easiest way to build and install *OpenSS7* packages from tarball is to use the tarball for the *OpenSS7 Master Package*, `openss7-0.9.2.G`.

### 6.2.1 Downloading with YUM

OpenSS7 repositories support `yum(8)` and `zypper(8)` in repomd XML format as well as YaST and YaST2 formats.

OpenSS7 includes virtual packages that ease the installation and removal of kernel modules, libraries and utilities. Downloading, configuration, building and installation for a single-kernel distribution installation is as easy as:

```
% sudo yum install strsock
```

This and additional packages for installation are detailed as follows:

`'strsock'` Install this package if you need the runtime `'strsock'` package.

```
% sudo yum install strsock
```

This will install the `'strsock'`, `'strsock-lib'` and `'strsock-KVERSION'` RPMs, where `'KVERSION'` is the highest version number kernel on your system.

Remove this package if you need to remove all vestages of the `'strsock'` package.

```
% sudo yum remove strsock
```

This will remove the `'strsock'`, `'strsock-lib'`, `'strsock-devel'`, `'strsock-KVERSION'` and `'strsock-devel-KVERSION'` RPMs for all kernels on your system.

`'strsock-devel'`

Install this package if you need the development `'strsock'` package.

```
% sudo yum install strsock-devel
```

This will install the `'strsock'`, `'strsock-lib'`, `'strsock-devel'`, `'strsock-KVERSION'` and `'strsock-devel-KVERSION'` RPMs, where `'KVERSION'` is the highest version number kernel on your system.

Remove this package if you do not need development capabilities for the `'strsock'` package for any kernel.

```
% sudo yum remove strsock-devel
```

This will remove the ‘strsock-devel’ and ‘strsock-devel-KVERSION’ RPMs for all kernels on your system.

‘strsock-2.4.20-28.7’

Install this package if you need the runtime ‘strsock’ for kernel version ‘2.4.20-28.7’. The value ‘2.4.20-28.7’ is just an example. For the running kernel, you can install the runtime ‘strsock’ components with:

```
% sudo yum install strsock-$(uname -r)
```

This will install the ‘strsock’, ‘strsock-lib’ and ‘strsock-2.4.20-28.7’ RPMs, where ‘2.4.20-28.7’ is the kernel version specified.

Remove this package if you no longer need the runtime ‘strsock’ for kernel version ‘2.4.20-28.7’. The value ‘2.4.20-28.7’ is just an example. For the running kernel, you can remove the runtime ‘strsock’ components with:

```
% sudo yum remove strsock-$(uname -r)
```

This will remove the ‘strsock-2.4.20-28.7’ and ‘strsock-devel-2.4.20-28.7’ RPMs, where ‘2.4.20-28.7’ is the kernel version specified. Also, if this is the last kernel for which ‘strsock’ was installed, the ‘strsock’ ‘strsock-lib’ and ‘strsock-devel’ RPMs will also be removed.

Note that this is a virtual package name: the actual RPMs installed or removed from the system is a kernel module package whose precise name will depend upon the system being used.

‘strsock-devel-2.4.20-28.7’

Install this package if you need the development ‘strsock’ package for kernel version ‘2.4.20-28.7’. The value ‘2.4.20-28.7’ is just an example. For the running kernel, you can install the kernel development ‘strsock’ components with:

```
% sudo yum install strsock-devel-$(uname -r)
```

This will install the ‘strsock’, ‘strsock-lib’, ‘strsock-devel’, ‘strsock-2.4.20-28.7’ and ‘strsock-devel-2.4.20-28.7’ RPMs, where ‘2.4.20-28.7’ is the kernel version specified.

Remove this package if you no longer need the development capabilities for the ‘strsock’ package for kernel version ‘2.4.20-28.7’. The value ‘2.4.20-28.7’ is just an example. For the running kernel, you can remove the kernel development ‘strsock’ components with:

```
% sudo yum remove strsock-devel-$(uname -r)
```

This will remove the ‘strsock-devel-2.4.20-28.7’ RPMs, where ‘2.4.20-28.7’ is the kernel version specified. Also, if this is the last kernel for which ‘strsock’ was installed, the ‘strsock-devel’ RPMs will also be removed.

Note that this is a virtual package name: the actual RPMs installed or removed from the system is a kernel module package whose precise name will depend upon the system being used.

**‘strsock-lib’**

This package is an auxillary package that should be removed and inserted automatically by `yum(8)`. In rare instances you might need to remove or install this package explicitly.

**6.2.2 Downloading with APT**

OpenSS7 repositories support `apt(8)` repository digests and signatures.

**6.2.3 Downloading the Binary RPM**

To install from binary RPM, you will need several of the RPM for a complete installation. Binary RPM fall into several categories. To download and install a complete package requires the appropriate RPM from each of the several categories below, as applicable. Some release packages do not provide RPMs in each of the several categories.

To install from Binary RPM, you will need all of the following kernel independent packages for your architecture, and one of the kernel-dependent packages from the next section.

**Independent RPM**

Independent RPM are dependent on neither the Linux kernel version, nor the *STREAMS* package. For example, the source package `‘strsock-source-0.9.2.4-1.7.2.noarch.rpm’`, is not dependent on kernel nor *STREAMS* package.

All of the following kernel and *STREAMS* independent RPM are required for your architecture. Binary RPMs listed here are for example only: additional binary RPMs are available from the downloads site. If your architecture is not available, you can build binary RPM from the source RPM (see see [Section 6.4.1 \[Building from the Source RPM\]](#), page 73).

**Architecture Independent****strsock-dev-0.9.2.4-1.7.2.noarch.rpm**

The `‘strsock-dev’` package contains the device definitions necessary to run applications programs developed for OpenSS7 *STREAMS* Sockets.<sup>1</sup>

**strsock-doc-0.9.2.4-1.7.2.noarch.rpm**

The `‘strsock-doc’` package contains this manual in plain text, postscript, `‘pdf’` and `‘html’` forms, along with the meta-information from the `‘strsock’` package. It also contains all of the manual pages necessary for developing OpenSS7 *STREAMS* Sockets applications and OpenSS7 *STREAMS* Sockets *STREAMS* modules or drivers.

**strsock-init-0.9.2.4-1.7.2.noarch.rpm**

The `‘strsock-init’` package contains the `init` scripts and provides the `‘postinst’` scripts necessary to create kernel module preloads and modules definitions for all kernel module `‘core’` subpackages.

<sup>1</sup> Not all distributions support the `‘%dev’` RPM macro: a case in point is the SuSE 8.0 distribution which uses an older version of `rpm(1)`. Distributions that do not support the `‘%dev’` macro will build devices as a `‘%post’` operation. Note also that not all release packages contain devices. Only packages that provide *STREAMS* character device drivers need devices, and then only when the `‘specfs’` or `‘devfsd’` is not being used.



**strsock-source-0.9.2.4-1.7.2.noarch.rpm**

The ‘**strsock-source**’ package contains the source code necessary for building the OpenSS7 STREAMS Sockets release. It includes the **autoconf(1)** configuration utilities necessary to create and distribute tarballs, ‘rpm’ and ‘deb’/‘dsc’.<sup>2</sup>

**Architecture Dependent****strsock-devel-0.9.2.4-1.7.2.i686.rpm**

The ‘**strsock-devel**’ package contains library archives for static compilation, header files to develop OpenSS7 STREAMS Sockets modules and drivers. This also includes the header files and static libraries required to compile OpenSS7 STREAMS Sockets applications programs.

**strsock-lib-0.9.2.4-1.7.2.i686.rpm**

The ‘**strsock-lib**’ package contains the run-time shared libraries necessary to run application programs and utilities developed for the ‘**strsock**’ package.<sup>3</sup>

**STREAMS-Dependent RPM**

*STREAMS*-Dependent RPM are dependent upon the specific *STREAMS* package being used, either *Linux STREAMS* or *Linux Fast-STREAMS*. Packages dependent upon *Linux STREAMS* will have ‘**LiS**’ in the package name. Packages dependent upon *Linux Fast-STREAMS* will have ‘**streams**’ in the package name. Note that some *STREAMS*-Dependent RPM are also Kernel-Dependent RPM as described below.

One of the following *STREAMS*-Dependent packages is required for your architecture. If your architecture is not on the list, you can build binary RPM from the source RPM (see see [Section 6.4.1 \[Building from the Source RPM\], page 73](#)).

**strsock-LiS-util-0.9.2.4-1.7.2.i686.rpm**

The ‘**strsock-LiS-util**’ package provides administrative and configuration test utilities and commands associated with the OpenSS7 STREAMS Sockets package. Because this package must link a *STREAMS*-specific library, it is a *STREAMS*-Dependent package. Use the ‘**strsock-LiS-util**’ package if you have *LiS* installed.

**strsock-streams-util-0.9.2.4-1.7.2.i686.rpm**

The ‘**strsock-streams-util**’ package provides administrative and configuration test utilities and commands associated with the OpenSS7 STREAMS Sockets package. Because this package must link a *STREAMS*-specific library, it is a *STREAMS*-Dependent package. Use the ‘**strsock-streams-util**’ package if you have *streams* installed.

**Kernel-Dependent RPM**

Kernel-Dependent RPM are dependent on specific Linux Kernel Binary RPM releases. Packages are provided for popular released *RedHat* kernels. Packages dependent upon *Red-*

<sup>2</sup> Note that not all releases have source RPM packages. Release packages that do not contain kernel modules do not generate a source RPM package.

<sup>3</sup> Note that not all release packages contain shared libraries, and, therefore, not all release packages contain this package.



*Hat* or other kernel RPM will have the ‘\_kversion’ kernel package version in the package name.

One of the following Kernel-Dependent packages is required for your architecture and kernel version. If your architecture or kernel version is not on the list, you can build binary RPM from the source RPM (see see [Section 6.4.1 \[Building from the Source RPM\]](#), page 73).<sup>4</sup>

#### [strsock-core-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm](#)

The ‘strsock-core’ package contains the loadable kernel modules that depend only on the kernel. This package is heavily tied to the kernel for which it was compiled. This particular package applies to kernel version ‘2.4.20-28.7’.<sup>5</sup>

#### [strsock-info-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm](#)

The ‘strsock-info’ package<sup>6</sup> contains the module symbol version information for the ‘core’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loading the actual kernel modules (from the ‘core’ subpackage above). This package is heavily tied to the kernel for which it was compiled. This particular package applies to kernel version ‘2.4.20-28.7’.<sup>7</sup>

#### [strsock-LiS-core-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm](#)

The ‘strsock-LiS-core’ package contains the kernel modules that provide the OpenSS7 STREAMS Sockets *STREAMS* modules and drivers. This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘LiS’ (*Linux STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>8</sup>

#### [strsock-streams-core-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm](#)

The ‘strsock-streams-core’ package contains the kernel modules that provide the OpenSS7 STREAMS Sockets *STREAMS* modules and drivers. This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘streams’ (*Linux Fast-STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>9</sup>

#### [strsock-LiS-info-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm](#)

The ‘strsock-LiS-info’ package<sup>10</sup> contains the module symbol version information for the ‘LiS-core’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loaded the

<sup>4</sup> Note that on *Mandrakelinux*, unlike other RPM kernel distributions, kernel packages for the i386 architectures are always placed in i586 architecture packages regardless of the true processor architecture of the kernel package. ‘configure’ detects this and builds the appropriate packages.

<sup>5</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example. Note also that only release packages that contain kernel modules will contain a ‘core’ subpackage.

<sup>6</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘info’ subpackage. Also, this subpackage is only applicable to 2.4 series kernels and is not necessary and not built for 2.6 series kernels.

<sup>7</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>8</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>9</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>10</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘LiS-info’ subpackage.

actual kernel modules (from the ‘`LiS-core`’ subpackage above). This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘`LiS`’ (*Linux STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>11</sup>

#### `strsock-streams-info-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm`

The ‘`strsock-streams-info`’ package<sup>12</sup> contains the module symbol version information for the ‘`streams-core`’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loaded the actual kernel modules (from the ‘`streams-core`’ subpackage above). This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘`streams`’ (*Linux Fast-STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>13</sup>

## Configuration and Installation

To configure, build and install the binary RPM, See [Section 6.3.1 \[Configuring the Binary RPM\]](#), page 58.

### 6.2.4 Downloading the Debian DEB

To install from binary DEB, you will need several of the DEB for a complete installation. Binary DEB fall into several categories. To download and install a complete package requires the appropriate DEB from each of the several categories below, as applicable. Some release packages do not provide DEBs in each of the several categories.

To install from Binary DEB, you will need all of the following kernel independent packages for your architecture, and one of the kernel-dependent packages from the next section.

### Independent DEB

Independent DEB are dependent on neither the Linux kernel version, nor the *STREAMS* package. For example, the source package ‘`strsock-source_0.9.2.4-0_i386.deb`’, is not dependent on kernel nor *STREAMS* package.

All of the following kernel and *STREAMS* independent DEB are required for your architecture. Binary DEBs listed here are for example only: additional binary DEBs are available from the downloads site. If your architecture is not available, you can build binary DEB from the Debian DSC (see see [Section 6.4.2 \[Building from the Debian DSC\]](#), page 74).

## Architecture Independent

#### `strsock-dev_0.9.2.4-0_all.deb`

The ‘`strsock-dev`’ package contains the device definitions necessary to run applications programs developed for OpenSS7 STREAMS Sockets.<sup>14</sup>

<sup>11</sup> Note that the ‘`_kversion`’ of ‘2.4.20-28.7’ is only an example.

<sup>12</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘`streams-info`’ subpackage.

<sup>13</sup> Note that the ‘`_kversion`’ of ‘2.4.20-28.7’ is only an example.

<sup>14</sup> Note that not all release packages contain devices. Only packages that provide *STREAMS* character device drivers need devices, and then only when the ‘`specfs`’ or ‘`devfsd`’ is not being used.

**strsock-doc\_0.9.2.4-0\_all.deb**

The ‘**strsock-doc**’ package contains this manual in plain text, postscript, ‘pdf’ and ‘html’ forms, along with the meta-information from the ‘**strsock**’ package. It also contains all of the manual pages necessary for developing OpenSS7 STREAMS Sockets applications and OpenSS7 STREAMS Sockets *STREAMS* modules or drivers.

**strsock-init\_0.9.2.4-0\_all.deb**

The ‘**strsock-init**’ package contains the `init` scripts and provides the `postinst` scripts necessary to create kernel module preloads and modules definitions for all kernel module ‘**core**’ subpackages.

**strsock-source\_0.9.2.4-0\_all.deb**

The ‘**strsock-source**’ package contains the source code necessary for building the OpenSS7 STREAMS Sockets release. It includes the `autoconf(1)` configuration utilities necessary to create and distribute tarballs, rpms and `deb/dscs`.<sup>15</sup>

## Architecture Dependent

**strsock-devel\_0.9.2.4-0\_i386.deb**

The ‘**strsock-devel**’ package contains library archives for static compilation, header files to develop OpenSS7 STREAMS Sockets modules and drivers. This also includes the header files and static libraries required to compile OpenSS7 STREAMS Sockets applications programs.

**strsock-lib\_0.9.2.4-0\_i386.deb**

The ‘**strsock-lib**’ package contains the run-time shared libraries necessary to run application programs and utilities developed for the ‘**strsock**’ package.<sup>16</sup>

## STREAMS-Dependent DEB

*STREAMS*-Dependent DEB are dependent upon the specific *STREAMS* package being used, either *Linux STREAMS* or *Linux Fast-STREAMS*. Packages dependent upon *Linux STREAMS* will have ‘**LiS**’ in the package name. Packages dependent upon *Linux Fast-STREAMS* will have ‘**streams**’ in the package name. Note that some *STREAMS*-Dependent DEB are also Kernel-Dependent DEB as described below.

One of the following *STREAMS*-Dependent packages is required for your architecture. If your architecture is not on the list, you can build binary DEB from the Debian DSC (see see Section 6.4.2 [Building from the Debian DSC], page 74).

**strsock-LiS-util\_0.9.2.4-0\_i386.deb**

The ‘**strsock-LiS-util**’ package provides administrative and configuration test utilities and commands associated with the OpenSS7 STREAMS Sockets package. Because this package must link a *STREAMS*-specific library, it is a *STREAMS*-Dependent package. Use the ‘**strsock-LiS-util**’ package if you have *LiS* installed.

<sup>15</sup> Note that not all releases have source DEB packages. Release packages that do not contain kernel modules do not generate a source DEB package.

<sup>16</sup> Note that not all release packages contain shared libraries, and, therefore, not all release packages contain this package.

**strsock-streams-util\_0.9.2.4-0\_i386.deb**

The ‘**strsock-streams-util**’ package provides administrative and configuration test utilities and commands associated with the OpenSS7 STREAMS Sockets package. Because this package must link a *STREAMS*-specific library, it is a *STREAMS*-Dependent package. Use the ‘**strsock-streams-util**’ package if you have streams installed.

**Kernel-Dependent DEB**

Kernel-Dependent DEB are dependent on specific Linux Kernel Binary DEB releases. Packages are provided for popular released *Debian* kernels. Packages dependent upon *Debian* or other kernel DEB will have the ‘**\_kversion**’ kernel package version in the package name.

One of the following Kernel-Dependent packages is required for your architecture and kernel version. If your architecture or kernel version is not on the list, you can build binary DEB from the source DEB (see see [Section 6.4.2 \[Building from the Debian DSC\], page 74](#)).<sup>17</sup>

**strsock-core-2.4.20-28.7\_0.9.2.4-0\_i386.deb**

The ‘**strsock-core**’ package contains the loadable kernel modules that depend only on the kernel. This package is heavily tied to the kernel for which it was compiled. This particular package applies to kernel version ‘2.4.20-28.7’.<sup>18</sup>

**strsock-info-2.4.20-28.7\_0.9.2.4-0\_i386.deb**

The ‘**strsock-info**’ package<sup>19</sup> contains the module symbol version information for the ‘**core**’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loading the actual kernel modules (from the ‘**core**’ subpackage above). This package is heavily tied to the kernel for which it was compiled. This particular package applies to kernel version ‘2.4.20-28.7’.<sup>20</sup>

**strsock-LiS-core-2.4.20-28.7\_0.9.2.4-0\_i386.deb**

The ‘**strsock-LiS-core**’ package contains the kernel modules that provide the OpenSS7 STREAMS Sockets *STREAMS* modules and drivers. This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘**LiS**’ (*Linux STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>21</sup>

**strsock-streams-core-2.4.20-28.7\_0.9.2.4-0\_i386.deb**

The ‘**strsock-streams-core**’ package contains the kernel modules that provide the OpenSS7 STREAMS Sockets *STREAMS* modules and drivers. This package is heavily tied to the *STREAMS* package and kernel for which it was com-

<sup>17</sup> Note that on *Mandrakelinux*, unlike other DEB kernel distributions, kernel packages for the ix86 architectures are always placed in i586 architecture packages regardless of the true processor architecture of the kernel package. ‘**configure**’ detects this and builds the appropriate packages.

<sup>18</sup> Note that the ‘**\_kversion**’ of ‘2.4.20-28.7’ is only an example. Note also that only release packages that contain kernel modules will contain a ‘**core**’ subpackage.

<sup>19</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘**info**’ subpackage. Also, this subpackage is only applicable to 2.4 series kernels and is not necessary and not built for 2.6 series kernels.

<sup>20</sup> Note that the ‘**\_kversion**’ of ‘2.4.20-28.7’ is only an example.

<sup>21</sup> Note that the ‘**\_kversion**’ of ‘2.4.20-28.7’ is only an example.

piled. This particular package applies to ‘streams’ (*Linux Fast-STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>22</sup>

#### strsock-LiS-info-2.4.20-28.7\_0.9.2.4-0\_i386.deb

The ‘strsock-LiS-info’ package<sup>23</sup> contains the module symbol version information for the ‘LiS-core’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loaded the actual kernel modules (from the ‘LiS-core’ subpackage above). This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘LiS’ (*Linux STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>24</sup>

#### strsock-streams-info-2.4.20-28.7\_0.9.2.4-0\_i386.deb

The ‘strsock-streams-info’ package<sup>25</sup> contains the module symbol version information for the ‘streams-core’ subpackage, above. It is possible to load this subpackage and compile modules that use the exported symbols without loaded the actual kernel modules (from the ‘streams-core’ subpackage above). This package is heavily tied to the *STREAMS* package and kernel for which it was compiled. This particular package applies to ‘streams’ (*Linux Fast-STREAMS*) on kernel version ‘2.4.20-28.7’.<sup>26</sup>

## Configuration and Installation

To configure, build and install the Debian DEB, See [Section 6.3.2 \[Configuring the Debian DEB\]](#), page 59.

### 6.2.5 Downloading the Source RPM

If you cannot obtain a binary RPM for your architecture, or would like to roll you own binary RPM, download the following source RPM.

#### strsock-0.9.2.4-1.src.rpm

This is the source RPM for the package. From this source RPM it is possible to build binary RPM for any supported architecture and for any 2.4 or 2.6 kernel, for either *Linux STREAMS* or *Linux Fast-STREAMS*.

## Configuration

To configure the source RPM, See [Section 6.3.3 \[Configuring the Source RPM\]](#), page 59.

### 6.2.6 Downloading the Debian DSC

If you cannot obtain a binary DEB for your architecture, or would like to roll your own DEB, download the following Debian DSC.

<sup>22</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>23</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘LiS-info’ subpackage.

<sup>24</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>25</sup> Note that only release packages that contain kernel modules and that export versioned symbols will contain a ‘streams-info’ subpackage.

<sup>26</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

[strsock-0.9.2.4-0.dsc](#)  
[strsock-0.9.2.4-0.tar.gz](#)

This is the Debian DSC for the package. From this Debian DSC it is possible to build binary DEB for any supported architecture and for any 2.4 or 2.6 kernel, for either *Linux STREAMS* or *Linux Fast-STREAMS*.

## Configuration

To configure the source RPM, See [Section 6.3.4 \[Configuring the Debian DSC\]](#), page 63.

### 6.2.7 Downloading the Tar Ball

For non-[rpm\(1\)](#) and non-[dpkg\(1\)](#) architectures, download the tarball as follows:

[strsock-0.9.2.4.tar.gz](#)  
[strsock-0.9.2.4.tar.bz2](#)

These are the [tar\(1\)](#) balls for the release. These [tar\(1\)](#) balls contain the [autoconf\(1\)](#) distribution which includes all the source necessary for building and installing the package. These tarballs will even build Source RPM and Binary RPM on [rpm\(1\)](#) architectures and Debian DSC and DEB on [dpkg\(1\)](#) architectures.

The tar ball may be downloaded easily with [wget\(1\)](#) as follows:

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
```

or

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.gz
```

Note that you will need an *OpenSS7 Project* user name and password to download release candidates (which are only available to subscribers and sponsors of the *OpenSS7 Project*).

## Unpacking the Archive

After downloading one of the tar balls, unpack the archive using one of the following commands:

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.gz  
% tar -xzvf strsock-0.9.2.4.tar.gz
```

or

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2  
% tar -xjvf strsock-0.9.2.4.tar.bz2
```

Either will create a subdirectory name 'strsock-0.9.2.4' containing all of the files and subdirectories for the `strsock` package.

## Configuration

To configure and install the tar ball, See [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63.

### 6.2.8 Downloading from CVS

If you are a subscriber or sponsor of [The OpenSS7 Project](#) with CVS archive access privileges then you can download release, mid-release or release candidate versions of the ‘`strsock`’ package from the project CVS archive.

The OpenSS7 STREAMS Sockets package is located in the ‘`strsock`’ module of ‘`/var/cvs`’. For release tag information, see [Chapter 5 \[Releases\]](#), page 33.

To access the archive from the project CVS pserver, use the following commands to check out a version from the archive:

```
% export CVSROOT='-d:pserver:username@cvs.openss7.com:2401/var/cvs'
% cvs login
Password: *****
% cvs co -r strsock_0.9.2.4 strsock
% cvs logout
```

It is, of course, possible to check out by date or by other criteria. For more information, see [`cvs\(1\)`](#).

## Preparing the CVS Working Directory

Although public releases of the ‘`strsock`’ package do not require reconfiguration, creating a configurable directory from the CVS archive requires tools not normally distributed with the other releases.

The build host requires the following GNU tools:

- `m4 1.4.12`
- `autoconf 2.63`
- `automake 1.10.1`
- `libtool 2.2.4`
- `gettext 0.17`
- `flex 2.5.33`
- `bison 2.3`

Most desktop development GNU/Linux distributions will have these tools; however, some non-development or server-style installations might not and they must be installed separately.<sup>27</sup>

Also, these tools can be acquired from the [FSF website](#) in the free software directory, and also at the following locations:

- [m4-1.4.12](#)
- [autoconf-2.63](#)

---

<sup>27</sup> Older version of bison (2.0) and the older version of flex (2.5.4a) are also suitable. Where possible, use the more recent bison 2.3 and flex 2.5.33.



- automake-1.10.1
- libtool-2.2.4
- gettext-0.17
- flex-2.5.33
- bison-2.3

It should be stressed that, in particular, the `autoconf(1)`, and `automake(1)`, must be at version releases 2.63 and 1.10.1. *The versions normally distributed in some mainstream GNU/Linux distributions are, in fact, much older than these versions.*<sup>28</sup> GNU version of these packages configured and installed to default directories will install in `‘/usr/local/’` allowing them to coexist with distribution installed versions.

For building documentation, the build host also requires the following documentation tools:

- gs 6.51 or ghostscript 6.51, or newer.
- tetex 3.0 or texlive 2007, or newer.
- texinfo 4.13a or newer.
- transfig 3.2.3d or newer.
- imagemagick 5.3.8 or ImageMagick 5.3.8, or newer.
- groff 1.17.2 or newer.
- gnuplot 3.7 or newer.
- latex2html 1.62 or newer.

Most desktop GNU/Linux distributions will have these tools; however, some server-style installations (e.g. *Ubuntu-server*, *SLES 9* or *Fedora 6* or *7*) will not and they must be installed separately.<sup>29</sup>

Note that `texinfo 4.12` must not be used as it breaks the build process.

For uncooked manual pages, the entire `groff(1)` package is required on older *Debian* and *Ubuntu* systems (the base package did not include `grefer(1)` which is used extensively by uncooked manual pages). The following will get what you need on older systems:

```
Debian: % apt-get install groff_ext
Ubuntu: % apt-get install groff
```

On newer systems, simply:

```
% apt-get install groff
```

In addition, the build host requires a complete tool chain for compiling for the target host, including kernel tools such as `genksyms(8)` and others.

<sup>28</sup> A notable exception is Debian and Fedora 7. Note that on Fedora 7 the `gettext-devel` package must be installed.

<sup>29</sup> In particular, for *CentOS*, *Fedora 6* or *7*, the `tetex-latex` and `gnuplot` packages must be loaded as well. Note also that the `latex2html` used to be part of the `textex` package (or subpackages) but is now often packaged on its own. Recent distributions such as SUSE 11.0 and Fedora 9 use the `texlive` package instead of the `texex` package.



If you wish to package ‘rpms’ on an `rpm(1)` system, or ‘debs’ on a `dpkg(1)` system, you will need the appropriate tool chain. Systems based on `rpm(1)` typically have the necessary tool chain available, however, `dpkg(1)` systems do not. The following on a *Debian* or *Ubuntu* system will get what you need:

```
% apt-get install debhelper
% apt-get install fakeroot
```

To generate a configuration script and the necessary scriptlets required by the GNU `autoconf(1)` system, execute the following commands on the working directory:

```
% autoreconf -fiv strsock
```

where, ‘strsock’ is the name of the directory to where the working copy was checked out under the previous step. This command generates the ‘configure’ script and other missing pieces that are normally distributed with the release Tar Balls, SRPMs and DSCs.

Make sure that ‘autoreconf --version’ returns ‘2.63’. Otherwise, you may need to perform something like the following:

```
% PATH="/usr/local/bin:$PATH"
% autoreconf -fiv strsock
```

After reconfiguring the directory, the package can then be configured and built using the same instructions as are used for the Tar Ball, see [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63, and [Section 6.4.3 \[Building from the Tar Ball\]](#), page 74.

Do note, however, that `make(1)` will rebuild the documentation that is normally released with the package. Additional tools may be necessary for building the documentation. To avoid building and installing the documentation, use the ‘--disable-devel’ or ‘--disable-docs’ option to configure described in [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63.

When configuring the package in a working directory and while working a change-compile-test cycle that involves configuration macros or documentation, I find it of great advantage to invoke the GNU ‘configure’ options ‘--enable-maintainer-mode’, ‘--enable-dependency-tracking’ and ‘--disable-devel’. The first of these three options will add maintainer-specific targets to any generated ‘Makefile’, the second option will invoke automatic dependency tracking within the ‘Makefile’ so rebuilds after changes to macro, source or documentation files will be automatically rebuilt; and the last option will suppress rebuilding and reinstalling documentation manual pages and header files. Header files will still be available under the ‘/usr/src’ directory.

## 6.3 Configuration

### 6.3.1 Configuring the Binary RPM

In general the binary RPM do not require any configuration, however, during installation it is possible to relocate some of the installation directories. This allows some degree of customization. Relocations that are available on the binary RPM are as follows:

```
'strsock-LiS-core-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm'
```

```
'strsock-streams-core-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm'
```

```
  '/lib/modules/2.4.20-28.7'
```

This relocatable directory contains the kernel modules that provide the strsock *STREAMS* core, drivers and modules.<sup>30</sup>

```
'strsock-LiS-info-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm'
```

```
'strsock-streams-info-2.4.20-28.7-0.9.2.4-1.7.2.i686.rpm'
```

```
  '/usr/include/strsock/2.4.20-28.7'
```

This relocatable directory contains the kernel module exported symbol information that allows other kernel modules to be compiled against the correct version of the strsock package.<sup>31</sup>

```
'strsock-dev-0.9.2.4-1.7.2.i686.rpm'
```

```
  (not relocatable)
```

```
'strsock-devel-0.9.2.4-1.7.2.i686.rpm'
```

```
  '/usr/lib'
```

This relocatable directory contains strsock libraries.

```
  '/usr/include/strsock'
```

This relocatable directory contains strsock header files.

```
'strsock-doc-0.9.2.4-1.7.2.i686.rpm'
```

```
  '/usr/share/doc'
```

This relocatable directory contains all package specific documentation (including this manual). The subdirectory in this directory is the 'strsock-0.9.2.4' directory.

```
  '/usr/share/info'
```

This relocatable directory contains info files (including the info version of this manual).

```
  '/usr/share/man'
```

This relocatable directory contains manual pages.

```
'strsock-LiS-lib-0.9.2.4-1.7.2.i686.rpm'
```

```
'strsock-streams-lib-0.9.2.4-1.7.2.i686.rpm'
```

```
  '/usr/lib'
```

This relocatable directory contains the run-time shared libraries necessary to run applications programs and utilities developed for OpenSS7 STREAMS Sockets.

<sup>30</sup> Note that the '\_kversion' of '2.4.20-28.7' is only an example.

<sup>31</sup> Note that the '\_kversion' of '2.4.20-28.7' is only an example. Also, note that the 'info' subpackage is only applicable to the 2.4 kernel series.

`‘/usr/share/locale’`  
This relocatable directory contains the locale information for shared library files.

`‘strsock-source-0.9.2.4-1.7.2.i686.rpm’`

`‘/usr/src’`  
This relocatable directory contains the source code.

`‘strsock-LiS-util-0.9.2.4-1.7.2.i686.rpm’`

`‘strsock-streams-util-0.9.2.4-1.7.2.i686.rpm’`

`‘/usr/bin’`  
This relocatable directory contains binary programs and utilities.

`‘/usr/sbin’`  
This relocatable directory contains system binary programs and utilities.

`‘/usr/libexec’`  
This relocatable directory contains test programs.

`‘/etc’` This relocatable directory contains `init` scripts and configuration information.

## Installation

To install the binary RPM, See [Section 6.5.1 \[Installing the Binary RPM\]](#), page 75.

### 6.3.2 Configuring the Debian DEB

In general the binary DEB do not require any configuration.

## Installation

To install the Debian DEB, See [Section 6.5.2 \[Installing the Debian DEB\]](#), page 76.

### 6.3.3 Configuring the Source RPM

When building from the source RPM (see [Section 6.4.1 \[Building from the Source RPM\]](#), page 73), the rebuild process uses a number of macros from the user’s `‘.rpmmacros’` file as described in [rpm\(8\)](#).

Following is an example of the `‘~/rpmmacros’` file that I use for rebuilding RPMS:

```

#
# RPM macros for building rpms
#

%vendor OpenSS7 Corporation
%distribution OpenSS7
%disturl http://www.openss7.org/
%packager Brian Bidulock <bidulock@openss7.org>
%url http://www.openss7.org/

%_signature gpg
%_gpg_path /home/brian/.gnupg
%_gpg_name openss7@openss7.org
%_gpgbin /usr/bin/gpg

%_source_payload w9.bzdio
%_binary_payload w9.bzdio

%_unpackaged_files_terminate_build 1
%_missing_doc_files_terminate_build 1
%_use_internal_dependency_generator 0
%_repackage_all_erasures 0
%_rollback_transaction_on_failure 0

%configure2_5x %configure
%make make

```

When building from the source RPM (see [Section 6.4.1 \[Building from the Source RPM\]](#), [page 73](#)), it is possible to pass a number of additional configuration options to the `rpmbuild(1)` process.

The additional configuration options are described below.

Note that distributions that use older versions of rpm do not have the ‘`--with`’ or ‘`--without`’ options defined. To achieve the same effect as:

```
--with someparm=somearg
```

do:

```
--define "_with_someparm --with-someparm=somearg"
```

This is a generic description of common `rpmbuild(1)` options. Not all `rpmbuild(1)` options are applicable to all SRPMs. Options that are kernel module specific are only applicable to SRPMs that build kernel modules. *STREAMS* options are only applicable to SRPMs that provide or require *STREAMS*.

```
--define "_kversion $PACKAGE_KVERSION"
```

Specifies the kernel version other than the running kernel for which to build. If `_kversion` is not defined when rebuilding, the environment variable `PACKAGE_KVERSION` is used. If the environment variable `PACKAGE_KVERSION` is not defined, then the version of the running kernel (i.e. discovered with ‘`uname -r`’) is used as the target version for kernel-dependent packages. This option can also be defined in an ‘`.rpmspec`’ file using the macro name ‘`_kversion`’.

`--with checks`

`--without checks`

Enable or disable preinstall checks. Each packages supports a number of preinstall checks that can be performed by invoking the ‘`check`’ target with `automake(1)`. These currently consist of checking each kernel module for unresolved kernel symbols, checking for documentation for exported kernel module symbols, checking for documentation for exported library symbols, checking for standard options for build and installable programs, checking for documentation for built and installable programs. Normally these checks are only run in maintainer mode, but can be enabled and disabled with this option.

`--with k-optimize=HOW`

`--without k-optimize`

Specify ‘`HOW`’ optimization, *normal*, *size*, *speed* or *quick*. *size* compiles kernel modules `-Os`, *speed* compiles kernel modules `-O3`, and *quick* compiles kernel modules `-O0`. The default is *normal*. Use with care.

`--with cooked-manpages`

`--without cooked-manpages`

Some systems do not like `grefer(1)` references in manual pages.<sup>32</sup> This option will cook `soelim(1)`, `refer(1)`, `tbl(1)` and `pic(1)` commands from the manual pages and also strip `groff(1)` comments. The default is to leave manual pages uncooked: they are actually smaller that way.

`--with public`

`--without public`

Release public packages or private packages. This option has no effect on the ‘`strsock`’ package. The default is to release public packages.

`--with k-debug`

`--without k-debug`

Specifies whether kernel debugging is to be performed on the build kernel modules. Mutually exclusive with `test` and `safe` below. This has the effect of removing static and inline attributes from functions and invoking all debugging macros in the code. The default is to not perform kernel debugging.

`--with k-test`

`--without k-test`

Specifies whether kernel testing is to be performed. Mutually exclusive with `debug` above and `safe` below. This has the effect of removing static and inline attributes from functions and invoking most debugging macros in the code. The default is to not perform kernel testing.

---

<sup>32</sup> In particular, some *Debian* systems do not load the `groff(1)` extensions package and do not have `grefer(1)` installed. Although this is an oversight on the configuration of the particular *Debian* system, we accomodate such misconfiguration with this feature.

`--with k-safe`

`--without k-safe`

Specifies whether kernel safety is to be performed. Mutually exclusive with `debug` and `test` above. This has the effect of invoking some more pedantic assertion macros in the code. The default is not to apply kernel safety.

`--with k-inline`

`--without k-inline`

Specifies whether kernel `inline` functions are to be placed inline. This has the effect of adding the `'-finline-functions'` flag to `CFLAGS` for compiling kernel modules. Linux 2.4 kernels are normally compiled `'-O2'` which does not respect the `inline` directive. This compiles kernel modules with `'-finline-functions'` to get closer to `'-O3'` optimization. For better optimization controls, See [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63.

`--with k-modversions`

`--without k-modversions`

Specifies whether kernel symbol versions are to be applied to symbols exported by package kernel modules. The default is to version exported module symbols. This package does not export symbols so this option has no effect.

`--with devfs`

`--without devfs`

Specifies whether the build is for a device file system daemon enabled system with autoloading, or not. The default is to build for `devfsd(1)` autoloading when `CONFIG_DEVFS_FS` is defined in the target kernel. The `'rebuild'` target uses this option to signal to the RPM spec file that the `'dev'` subpackage need not be built. This option does not appear when the package has no devices.

`--with devel`

`--without devel`

Specifies whether to build development environment packages such as those that include header files, static libraries, manual pages and `texinfo(1)` documentation. The default is to build development environment packages. This option can be useful when building for an embedded target where only the runtime components are desired.

`--with docs`

`--without docs`

Specifies whether to build and install major documentation such manual pages and `texinfo(1)` documentation. The default is to build and install documentation. This option can be useful when building for an embedded target where only the runtime and static compile components are desired, but not major documentation. This option does not override the setting of `--without devel`.

`--with tools`

`--without tools`

Specifies whether user space packages are to be built. The default is to build user space packages. This option can be useful when rebuilding for multiple architectures and target kernels. The `'rebuild'` `automake(1)` target uses this

feature when rebuilding for all available architectures and kernels, to rebuild user packages once per architecture instead of once per kernel.

`--with modules`

`--without modules`

Specifies whether kernel modules packages are to be built. The default is to build kernel module packages. This option can be useful when rebuilding for multiple architectures and target kernels. The ‘rebuild’ `automake(1)` target uses this feature to rebuild for all available architectures and kernels.

`--with lis`

`--without lis`

Specifies that the package is to be rebuilt against *Linux STREAMS*. The default is to automatically identify whether ‘`LiS`’ or ‘`streams`’ is loaded on the build system and build accordingly.

`--with lfs`

`--without lfs`

Specifies that the package is to be rebuilt against *Linux Fast-STREAMS*. The default is to automatically identify whether ‘`LiS`’ or ‘`streams`’ is loaded on the build system and build accordingly.

In general, the default values of these options are sufficient for most purposes and no options need be provided when rebuilding the Source RPMs.

## Build

To build from the source RPM, See [Section 6.4.1 \[Building from the Source RPM\]](#), page 73.

### 6.3.4 Configuring the Debian DSC

The Debian DSC can be configured by passing options in the environment variable `BUILD_DEBOPTIONS`. The options placed in this variable take the same form as those passed to the ‘`configure`’ script, See [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63. For an example, See [Section 6.4.2 \[Building from the Debian DSC\]](#), page 74.

## Build

To build from the Debian DSC, See [Section 6.4.2 \[Building from the Debian DSC\]](#), page 74.

### 6.3.5 Configuring the Tar Ball

All of the normal GNU `autoconf(1)` configuration options and environment variables apply. Additional options and environment variables are provided to tailor or customize the build and are described below.

#### 6.3.5.1 Configure Options

This is a generic description of common ‘`configure`’ options that are in addition to those provided by `autoconf(1)`, `automake(1)`, `libtool(1)` and `gettext(1)`.

Not all ‘`configure`’ options are applicable to all release packages. Options that are kernel module specific are only applicable to release packages that build kernel modules. *STREAMS* options are only applicable to release packages that provide or require *STREAMS*.

Following are the additional ‘configure’ options, their meaning and use:

`--enable-checks`

`--disable-checks`

Enable or disable preinstall checks. Each release package supports a number of preinstall checks that can be performed by invoking the ‘check’ target with `make(1)`. These currently consist of checking each kernel module for unresolved kernel symbols, checking for documentation for exported kernel module symbols, checking for documentation for exported library symbols, checking for standard options for build and installable programs, checking for documentation for built and installable programs. Normally these checks are only run in maintainer mode, but can be enabled and disabled with this option.

`--enable-autotest`

`--disable-autotest`

Enable or disable pre- and post-installation testing. Each release package supports a number of `autotest` test suites that can be performed by invoking the ‘installcheck’ target with `make(1)`. These currently consist of running installed modules, commands and binaries against a number of specific test cases. Normally these checks are only run in maintainer mode, but can be enabled and disabled with this option.

`--disable-compress-manpages`

Compress manual pages with ‘gzip -9’ or ‘bzip2 -9’ or leave them uncompressed. The default is to compress manual pages with ‘gzip -9’ or ‘bzip2 -9’ if a single compressed manual page exists in the target installation directory (‘--mandir’). This disables automatic compression.

`--disable-public`

Disable public release. This option is not usable on public releases and only has a usable effect on OpenSS7 STREAMS Sockets when the package is acquired from CVS. In particular, the *STREAMS SS7/VoIP/ISDN/SIGTRAN Stacks* (`strss7-0.9a.8`) release package has a large number of non-public components. Specifying this option will cause the package to build and install all private release components in addition to the public release components. This option affects all release packages. Most release packages do not have private release components.

`--disable-initscripts`

Disables the installation of `init` scripts. The default is to configure and install `init` scripts and their associated configuration files.

Although the default is to install `init` scripts, installation attempts to detect a System V `init` script configuration, and if one is not found, the `init` scripts are installed into the appropriate directories, but the symbolic links to the run level script directories are not generated and the script is not invoked. Therefore, it is safe to leave this option unchanged, even on distributions that do not support System V `init` script layout.

`--disable-32bit-libs`

Disables the build and install of 32-bit compatibility libraries and test binaries on 64-bit systems that support 32-bit compatibility. The default is to build



and install 32-bit compatibility libraries and test binaries. This option can be useful when configuring for an embedded target where only native shared libraries and binaries are desired.

#### `--disable-devel`

Disables the installation of development environment components such as header files, static libraries, manual pages and `texinfo(1)` documentation. The default is to install development environment components. This option can be useful when configuring for an embedded target where only the runtime components are desired, or when performing a `edit-compile-test` cycle.

#### `--disable-docs`

Disables the build and installation of major documentation such manual pages and `texinfo(1)` documentation. The default is to build and install documentation. This option can be useful when building for an embedded target where only the runtime and static compile components are desired, but not major documentation. This option does not override the setting of `'--disable-devel'`.

#### `--enable-tools`

Specifies whether user space programs and libraries are to be built and installed. The default is to build and install user space programs and libraries. This option can be useful when rebuilding for multiple architectures and target kernels, particularly under `rpm(1)` or `dpkg(1)`. The `'rebuild'` `automake(1)` target uses this feature when rebuilding RPMs for all available architectures and kernels, to rebuild user packages once per architecture instead of once per kernel.

#### `--enable-modules`

Specifies whether kernel modules are to be built and installed. The default is to build and install kernel modules. This option can be useful when rebuilding for multiple architectures and target kernels, particularly under `rpm(1)` or `dpkg(1)`. The `'rebuild'` `automake(1)` target uses this feature to rebuild for all available architectures and kernels. This option has no effect for release packages that do not provide kernel modules.

#### `--enable-arch`

Specifies whether architectural dependent package components are to be built and installed. This option can be useful when rebuilding for multiple architectures and target kernels, particularly under `dpkg(1)`. The default is to configure, build and install architecture dependent package components. This option has no effect for release packages that do not provide architecture dependent components.

#### `--enable-indep`

Specifies whether architecture independent package components are to be built and installed. This option can be useful when rebuilding for multiple architectures and target kernels, particularly under `dpkg(1)`. The default is to configure, build and install architecture independent package components. This options has no effect for release packages that do not provide architecture independent components.

**--enable-k-inline**

Enable kernel inline functions. Most Linux kernels build without `'-finline-functions'`. This option adds the `'-finline-functions'` and `'-Winline'` flags to the compilation of kernel modules. Use with care. This option has no effect for release packages that do not provide kernel modules.

**--enable-k-safe**

Enable kernel module run-time safety checks. Specifies whether kernel safety is to be performed. This option is mutually exclusive with `'--enable-k-test'` and `'--enable-k-debug'` below. This has the effect of invoking some more pedantic assertion macros in the code. The default is not to apply kernel safety. This option has no effect for release packages that have are no kernel modules.

**--enable-k-test**

Enable kernel module run-time testing. Specifies whether kernel testing is to be performed. This option is mutually exclusive with `'--enable-k-safe'` above and `'--enable-k-debug'` below. This has the effect of remove `static` and `inline` attributes from functions and invoking most non-performance affecting debugging macros in the code. The default is not to perform kernel testing. This option has no effect for release packages that do not provide kernel modules.

**--enable-k-debug**

Enable kernel module run-time debugging. Specifies whether kernel debugging is to be performed. This option is mutually exclusive with `'--enable-k-safe'` and `'--enable-k-test'` above. This has the effect of removing `static` and `inline` attributes from functions and invoking all debugging macros in the code (including performance-affecting debug macros). The default is to not perform kernel debugging. This option has no effect for release packages that do not provide kernel modules.

**--disable-k-modversions**

Disable module versions on `strsock` symbols. Specifies whether kernel symbol versions are to be used on symbols exported from built `strsock` modules. The default is to provide kernel symbol versions on all exported symbols. This option has no effect for release packages that do not provide kernel modules.

**--enable-devfs****--disable-devfs**

Specifies whether the build is for a device file system daemon enabled system with autoloading, or not. The default is to build for `devfsd(8)` autoloading when `CONFIG_DEVFS_FS` is defined in the target kernel. The `'reuild automake(1)'` target uses this option to signal to the RPM spec file that the `'dev'` subpackage need not be built. This option has no effect for release packages that do not provide devices.

**--with-gpg-user=GNUPGUSER**

Specify the `gpg(1)` `'GNUPGUSER'` for signing RPMs and tarballs. The default is the content of the environment variable `GNUPGUSER`. If unspecified, the `gpg(1)` program will normally use the user name of the account invoking the `gpg(1)` program. For building source RPMs, the RPM macro `'_gpg_name'` will override this setting.

- `--with-gpg-home=GNUPGHOME`  
Specify the ‘GNUPGHOME’ directory for signing RPMs and tarballs. The default is the user’s ‘~/gpg’ directory. For building source RPMs, the RPM macro ‘\_gpg\_path’ will override this setting.
- `--with-pkg-epoch=EPOCH`  
Specifies the epoch for the package. This is neither used for `rpm(1)` nor `dpkg(1)` packages, it applies to the tarball release as a whole. The default is the contents of the ‘.pkgepoch’ file in the release package source directory or, if that file does not exist, zero (0).
- `--with-pkg-release=RELEASE`  
Specifies the release for the package. This is neither used for `rpm(1)` nor `dpkg(1)` packages, it applies to the tarball release as a whole. The default is the contents of the ‘.pkgrelease’ file in the release package source directory or, if that file does not exist, one (1). This is the number after the last point in the package version number.
- `--with-pkg-distdir=DIR`  
Specifies the distribution directory for the package. This is used by the maintainer for building distributions of tarballs. This is the directory into which archives are copied for distribution. The default is the top build directory.
- `--with-cooked-manpages`  
Convert manual pages to remove macro dependencies and `refer(1)` references. Some systems do not like `refer(1)` references in manual pages.<sup>33</sup> This option will cook `soelim(1)`, `refer(1)`, `tbl(1)` and `pic(1)` commands from the manual pages and also strip `groff(1)` comments. The default is to leave manual pages uncooked (they are actually smaller that way).
- `--with-rpm-epoch=PACKAGE_EPOCH`  
Specify the ‘PACKAGE\_EPOCH’ for the RPM spec file. The default is to use the RPM epoch contained in the release package file ‘.rpmepoch’.
- `--with-rpm-release=PACKAGE_RPMRELEASE`  
Specify the ‘PACKAGE\_RPMRELEASE’ for the RPM ‘spec’ file. The default is to use the RPM release contained in the release package file ‘.rpmrelease’.
- `--with-rpm-extra=PACKAGE_RPMEXTRA`  
Specify the ‘PACKAGE\_RPMEXTRA’ extra release information for the RPM spec file. The default is to use the RPM extra release information contained in the release package file ‘.rpmextra’. Otherwise, this value will be determined from automatic detection of the RPM distribution.
- `--with-rpm-topdir=PACKAGE_RPMTOPDIR`  
Specify the ‘PACKAGE\_RPMTOPDIR’ top directory for RPMs. If specified with a null ‘PACKAGE\_RPMTOPDIR’, the default directory for the RPM distribution will be used. If this option is not provided on the command line, the top build directory will be used as the RPM top directory as well.

---

<sup>33</sup> In particular, some *Debian* or *Ubuntu* systems do not load the `groff(1)` extensions package and do not have `refer(1)` installed. Although this is an oversight on the configuration of the particular *Debian* or *Ubuntu* system, we accomodate such misconfiguration with this feature.

- with-deb-epoch=EPOCH**  
Specify the 'PACKAGE\_DEBEPOCH' for the DEB control file. The default is to use the DEB epoch contained in the release package file '.debepoch'.
- with-deb-release=RELEASE**  
Specify the 'PACKAGE\_DEBRELEASE' for the DEB control file. The default is to use the DEB release contained in the release package file '.debrelease'.
- with-deb-topdir=DIR**  
Specify the 'PACKAGE\_DEBTOPDIR' top directory for DEBs. If specified with a null 'PACKAGE\_DEBTOPDIR', the default directory for the DEB distribution will be used. If this option is not provided on the command line, the top build directory will be used as the DEB top directory as well.
- with-k-release=PACKAGE\_KRELEASE**  
Specify the 'PACKAGE\_KRELEASE' release of the Linux kernel for which the build is targeted. When not cross compiling, if this option is not set, the build will be targeted at the kernel running in the build environment (e.g., 'uname -r'). When cross-compiling this option must be specified or the configure script will generate an error and terminate.
- with-k-linkage=PACKAGE\_KLINKAGE**  
Specify the 'PACKAGE\_KLINKAGE' for kernel module linkage. This can be one of the following:
- 'loadable' – loadable kernel modules
  - 'linkable' – linkable kernel objects
- The default is to build loadable kernel modules.
- with-k-modules=K-MODULES-DIR**  
Specify the 'K-MODULES-DIR' directory to which kernel modules will be installed. The default is based on the option '--with-k-release', '--with-k-prefix' and '--with-k-rootdir'. The default is 'DESTDIR/K-MODULES-DIR' which is typically 'DESTDIR/lib/modules/PACKAGE\_KRELEASE/'. This directory is normally located by the 'configure' script and need only be provided for special cross-build environments or when requested by a 'configure' script error message.
- with-k-build=K-BUILD-DIR**  
Specify the 'K-BUILD-DIR' base kernel build directory in which configured kernel source resides. The default is 'DESTDIR/K-MODULES-DIR/build'. This directory is normally located by the 'configure' script and need only be provided for special cross-build environments or when requested by a 'configure' script error message.
- with-k-source=K-SOURCE-DIR**  
Specify the 'K-SOURCE-DIR' base kernel build directory in which configured kernel source resides. The default is 'DESTDIR/K-MODULES-DIR/source'. This directory is normally located by the 'configure' script and need only be provided for special cross-build environments or when requested by a 'configure' script error message.

`--with-k-modver=K-MODVER-FILE`

Specify the ‘K-MODVER-FILE’ kernel module versions file. The default is ‘K-BUILD-DIR/Module.symvers’. This file is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message.

`--with-k-sysmap=K-SYSMAP-FILE`

Specify the ‘K-SYSMAP-FILE’ kernel system map file. The default is ‘K-BUILD-DIR/System.map’. This file is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message.

`--with-k-archdir=K-ARCHDIR`

Specify the ‘K-ARCHDIR’ kernel source architecture specific directory. The default is ‘DESTDIR/K-SOURCE-DIR/arch’. This directory is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message.

`--with-k-machdir=K-MACHDIR`

Specify the ‘K-MACHDIR’ kernel source machine specific directory. The default is ‘DESTDIR/K-SOURCE-DIR/target\_cpu’. This directory is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message.

`--with-k-config=K-CONFIG`

Specify the ‘K-CONFIG’ kernel configuration file. The default is ‘BOOT/config-K-RELEASE’. This configuration file is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message.

`--with-k-optimize=HOW`

`--without-k-optimize`

Specify ‘HOW’ optimization, *normal*, *size*, *speed* or *quick*. *size* compiles kernel modules `-Os`, *speed* compiles kernel modules `-O3`, and *quick* compiles kernel modules `-O0`. The default is *normal*. Use with care. The most common use of this option is to specify ‘`--with-k-optimize=speed --disable-k-safe`’ to compile for maximum performance. Nevertheless, even these setting are *ricing* and the resulting kernel modules will only be about 5% faster.

`--with-lis[=LIS-DIR]`

`--without-lis`

Specify the ‘LIS-DIR’ directory in which to find *LiS* headers. Also specifies that the build is to be made against Linux *STREAMS*. The default is ‘`/usr/include/LiS`’ if it exists, ‘no’ otherwise. This directory is normally located by the ‘configure’ script and need only be provided for special cross-build environments or when requested by a ‘configure’ script error message. This option has no effect on release packages that do not use the *STREAMS* subsystem.

`--with-lfs [=LFS-DIR]`

`--without-lfs`

Specify the 'LFS-DIR' directory in which to find *LFS* headers. Also specifies that the build is to be made against Linux Fast-STREAMS. The default is '/usr/include/streams' if it exists, 'no' otherwise. This directory is normally located by the 'configure' script and need only be provided for special cross-build environments or when requested by a 'configure' script error message. This option has no effect on release packages that do not use the *STREAMS* subsystem.

`--with-strconf-master=STRCONF_CONFIG`

Specify the 'STRCONF\_CONFIG' file name to which the configuration master file is written. The default is 'Config.master'. This option has no effect on release packages that do not use the *STREAMS* subsystem and the strconf scripts. This option should not be specified when configuring the master package as the setting for all add-on packages will conflict.

`--with-base-major=STRCONF_MAJBASE`

Start numbering for major devices at 'STRCONF\_MAJBASE'. The default is '230'. This option has no effect on release packages that do not use the *STREAMS* subsystem and the strconf scripts. This option should not be specified when configuring the master package as the setting for all add-on packages will conflict.

### 6.3.5.2 Environment Variables

Following are additional environment variables to 'configure', their meaning and use:

*GPG* GPG signature command. This is used for signing distributions by the maintainer. By default, 'configure' will search for this tool.

*GNUPGUSER*

GPG user name. This is used for signing distributions by the maintainer.

*GNUPGHOME*

GPG home directory. This is used for signing distributions by the maintainer.

*GPGPASSWD*

GPG password for signing. This is used for signing distributions by the maintainer. This environment variable is not maintained by the 'configure' script and should only be used on an isolated system.

*SOELIM* Roff source elimination command, `soelim(1)`. This is only necessary when the option '--with-cooked-manpages' has been specified and 'configure' cannot find the proper `soelim(1)` command. By default, 'configure' will search for this tool.

*REFER* Roff references command, `refer(1)`. This is only necessary when the option '--with-cooked-manpages' has been specified and 'configure' cannot find the proper `refer(1)` command. By default, 'configure' will search for this tool.

*TBL* Roff table command, `tbl(1)`. This is only necessary when the option '--with-cooked-manpages' has been specified and 'configure' cannot find the proper `tbl(1)` command. By default, 'configure' will search for this tool.



**PIC** Roff picture command, `pic(1)`. This is only necessary when the option ‘`--with-cooked-manpages`’ has been specified and ‘`configure`’ cannot find the proper `pic(1)` command. By default, ‘`configure`’ will search for this tool.

**GZIP** Default compression options provided to `GZIP_CMD`.

#### **GZIP\_CMD**

Manpages (and kernel modules) compression commands, `gzip(1)`. This is only necessary when the option ‘`--without-compressed-manpages`’ has *not* been specified and ‘`configure`’ cannot find the proper `gzip(1)` command. By default, ‘`configure`’ will search for this tool.

**BZIP2** Default compression options provided to `BZIP2_CMD`

#### **BZIP2\_CMD**

Manpages compression commands, `bzip2(1)`. This is only necessary when the option ‘`--without-compressed-manpages`’ has *not* been specified and ‘`configure`’ cannot find the proper `bzip2(1)` command. By default, ‘`configure`’ will search for this tool.

#### **MAKEWHATIS**

Manpages apropos database rebuild command, `makewhatis(8)`. By default, ‘`configure`’ will search for this tool. By default, ‘`configure`’ will search for this tool.

#### **CHKCONFIG**

Chkconfig command, `chkconfig(8)`. This was used for installation of `init` scripts. All packages now come with `init_install(8)` and `init_remove(8)` scripts used to install and remove `init` scripts on both RPM and Debian systems.

**RPM** Rpm command, `rpm(1)`. This is only necessary for RPM builds. By default, ‘`configure`’ will search for this tool.

#### **RPMBUILD**

Build RPM command, `rpmbuild(1)`. This is only necessary for RPM builds. By default, ‘`configure`’ will search for this tool. `rpm(1)` will be used instead of `rpmbuild(1)` only if `rpmbuild(1)` cannot be found.

**DPKG** Dpkg comand, `dpkg(1)`. This command is used for building Debian packages. By default, ‘`configure`’ will search for this tool.

#### **DPKG\_SOURCE**

Dpkg-source command, `dpkg-source(1)`. This command is used for building Debian dsc packages. By default, ‘`configure`’ will search for this tool.

#### **DPKG\_BUILDPACKAGE**

Dpkg-buildpackage command, `dpkg-buildpackage(1)`. This command is used for building Debian deb packages. By default, ‘`configure`’ will search for this tool.

#### **DEB\_BUILD\_ARCH**

Debian build architecture. This variable is used for building Debian packages. The default is the autoconf build architecture.

*DEB\_BUILD\_GNU\_CPU*

Debian build cpu. This variable is used for building Debian packages. The default is the autoconf build cpu.

*DEB\_BUILD\_GNU\_SYSTEM*

Debian build os. This variable is used for building Debian packages. The default is the autoconf build os.

*DEB\_BUILD\_GNU\_TYPE*

Debian build alias. This variable is used for building Debian packages. The default is the autoconf build alias.

*DEB\_HOST\_ARCH*

Debian host architecture. This variable is used for building Debian packages. The default is the autoconf host architecture.

*DEB\_HOST\_GNU\_CPU*

Debian host cpu. This variable is used for building Debian packages. The default is the autoconf host cpu.

*DEB\_HOST\_GNU\_SYSTEM*

Debian host os. This variable is used for building Debian packages. The default is the autoconf host os.

*DEB\_HOST\_GNU\_TYPE*

Debian host alias. This variable is used for building Debian packages. The default is the autoconf host alias.

*LDCONFIG*

Configure loader command, *ldconfig(8)*. Command used to configure the loader when libraries are installed. By default, 'configure' will search for this tool.

*DESTDIR* Cross build root directory. Specifies the root directory for build and installation.

*DEPMOD*

Build kernel module dependencies command, *depmod(8)*. This is used during installation of kernel modules to a running kernel to rebuild the modules dependency database. By default, 'configure' will search for this tool.

*MODPROBE*

Probe kernel module dependencies command, *modprobe(8)*. This is used during installation of kernel modules to a running kernel to remove old modules. By default, 'configure' will search for this tool.

*LSMOD*

List kernel modules command, *lsmod(8)*. This is used during installation of kernel modules to a running kernel to detect old modules for removal. By default, 'configure' will search for this tool.

*LSOF*

List open files command, *lsof(1)*. This is used during installation of kernel modules to a running kernel to detect old modules for removal. Processes owning the old kernel modules will be killed and the module removed. If the process restarts, the new module will be demand loaded. By default, 'configure' will search for this tool.



**GENKSYMS**

Generate kernel symbols command, `genksyms(8)`. This is used for generating module symbol versions during build. By default, ‘configure’ will search for this tool.

**KGENKSYMS**

Linux 2.6 generate kernel symbols command, `genksyms(8)`. This is used for generating module symbol version during build. By default, ‘configure’ will search for this tool.

**OBJDUMP**

Object dumping command, `objdump(1)`. This is used for listing information about object files. By default, ‘configure’ will search for this tool.

**NM**

Object symbol listing command, `nm(1)`. This is used for listing information about object files. By default, ‘configure’ will search for this tool.

**MODPOST\_CACHE**

Cache file for `modpost(1)`. The version of the `modpost.sh` script that ships with each package can cache information to a cache file to speed multiple builds. This environment variable is used to specify a cache file.

**AUTOM4TE**

Autom4te command, `autom4te(1)`. This is the executable used by `autotest` for pre- and post-installation checks. By default, ‘configure’ will search for this tool.

**AUTOTEST**

Autotest macro build command, `autom4te(1)`. This is the executable used by `autotest` for pre- and post-installation checks. By default, ‘configure’ will search for this tool.

**6.3.5.3 Build**

To build from the tar ball, See [Section 6.4.3 \[Building from the Tar Ball\]](#), page 74.

**6.4 Building****6.4.1 Building from the Source RPM**

If you have downloaded the necessary source RPM (see [Section 6.2.5 \[Downloading the Source RPM\]](#), page 53), then the following instructions will rebuild the binary RPMs on your system. Once the binary RPMs are rebuilt, you may install them as described above (see [Section 6.5.1 \[Installing the Binary RPM\]](#), page 75).

The source RPM is rebuilt to binary RPMs as follows:

```
% wget http://www.openss7.org/rpms/SRPMS/strsock-0.9.2.4-1.src.rpm
% rpmbuild --rebuild -vv strsock-0.9.2.4-1.src.rpm
```

The rebuild process can also recognize a number of options that can be used to tweak the resulting binaries, See [Section 6.3.3 \[Configuring the Source RPM\]](#), page 59. These options are provided on the `rpm(1)` command line. For example:

```
% rpmbuild --rebuild -vv --target athlon-redhat-linux \
--define "_kversion 2.4.20-28.7" \
--with lfs -- strsock-0.9.2.4-1.src.rpm
```

will rebuild binary RPM for the ‘2.4.20-28.7’ kernel for the ‘athlon’ architecture against the *Linux Fast-STREAMS STREAMS* package.<sup>34</sup>

## Installation

To install the resulting binary RPM, See [Section 6.5.1 \[Installing the Binary RPM\]](#), page 75.

### 6.4.2 Building from the Debian DSC

If you have downloaded the necessary Debian DSC (see [Section 6.2.6 \[Downloading the Debian DSC\]](#), page 53), then the following instructions will rebuild the binary DEBs on your system. Once the binary DEBs are rebuilt, you may install them as described above (see [Section 6.5.2 \[Installing the Debian DEB\]](#), page 76).

The Debian DSC is rebuilt to binary DEBs as follows:

```
% wget http://www.openss7.org/debian/strsock_0.9.2.4-0.dsc
% wget http://www.openss7.org/debian/strsock_0.9.2.4-0.tar.gz
% dpkg-buildpackage -v strsock_0.9.2.4-0.dsc
```

The rebuild process can also recognize a number of options that can be used to tweak the resulting binaries, See [Section 6.3.4 \[Configuring the Debian DSC\]](#), page 63. These options are provided in the environment variable *BUILD\_DPKG\_OPTIONS* and have the same form as the options to ‘configure’, See [Section 6.3.5 \[Configuring the Tar Ball\]](#), page 63. For example:

```
% BUILD_DEBOPTIONS='
--with-lfs
--with-k-release=2.4.20-28.7
--host=athlon-debian-linux-gnu'
dpkg-buildpackage -v \
strsock_0.9.2.4-0.dsc
```

will rebuild binary DEB for the ‘2.4.20-28.7’ kernel for the ‘athlon’ architecture against the *Linux Fast-STREAMS STREAMS* package.<sup>35</sup>

## Installation

To install the resulting binary DEB, See [Section 6.5.2 \[Installing the Debian DEB\]](#), page 76.

### 6.4.3 Building from the Tar Ball

If you have downloaded the tar ball (see [Section 6.2.7 \[Downloading the Tar Ball\]](#), page 54), then the following instructions will rebuild the package on your system. (Note that the build process does not required root privilege.)

<sup>34</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

<sup>35</sup> Note that the ‘\_kversion’ of ‘2.4.20-28.7’ is only an example.

### 6.4.3.1 Native Build

Following is an example of a native build against the running kernel:

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure
% make
% popd
```

### 6.4.3.2 Cross-Build

Following is an example for a cross-build. The kernel release version must always be specified for a cross-build.<sup>36</sup> If you are cross-building, specify the root for the build with environment variable `DESTDIR`. The cross-compile host must also be specified if different from the build host. Either the compiler and other tools must be in the usual places where GNU `autoconf(1)` can find them, or they must be specified with declarations such as `'CC=/usr/lib/ppc-linux/gcc'` on the `'configure'` command line.

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure DESTDIR="/some/other/root" \
--with-k-release=2.4.18 --host sparc-linux
% make
% popd
```

## 6.5 Installing

### 6.5.1 Installing the Binary RPM

If you have downloaded the necessary binary RPMs (see [Section 6.2.3 \[Downloading the Binary RPM\]](#), page 47), or have rebuilt binary RPMs using the source RPM (see [Section 6.4.1 \[Building from the Source RPM\]](#), page 73), then the following instructions will install the RPMs on your system. For additional information on `rpm(1)`, see `rpm(8)`.

```
% pushd RPMS/i686
% rpm -ihv strsock-*-0.9.2.4-1.7.2.i686.rpm
```

You must have the correct binary RPMs downloaded or built for this to be successful.

Some of the packages are relocatable and can have final installation directories altered with the `'--relocate'` option to `rpm(1)`, see `rpm(8)`. For example, the following will relocate the documentation and info directories:

<sup>36</sup> Because it *is* a cross-build, the kernel version on the build machine is unlikely to be the kernel version of the target machine, except by coincidence.

```
% pushd RPMS/i686
% rpm -ihv \
    --relocate '/usr/share/doc=/usr/local/share/doc' \
    --relocate '/usr/share/info=/usr/local/share/info' \
    -- strsock-doc-0.9.2.4-1.7.2.i686.rpm
```

The previous example will install the ‘strsock-doc’ package by will relocate the documentation an info directory contents to the ‘usr/local’ version.

### 6.5.2 Installing the Debian DEB

If you have downloaded the necessary Debian DEBs (see [Section 6.2.4 \[Downloading the Debian DEB\]](#), page 50), or have rebuild binary DEBs using the Debian DSC (see [Section 6.4.2 \[Building from the Debian DSC\]](#), page 74), then the following instructions will install the DEBs on your system. For additional information see [dpkg\(8\)](#).

```
% pushd debian
% dpkg -iv strsock-*_0.9.2.4-0_*.deb
```

You must have the correct ‘.deb’ files downloaded or build for this to be successful.

### 6.5.3 Installing the Tar Ball

After the build process (see [Section 6.4.3 \[Building from the Tar Ball\]](#), page 74), installation only requires execution of one of two [automake\(1\)](#) targets:

```
‘make install’
```

The ‘install’ [automake\(1\)](#) target will install all the components of the package. Root privilege is required to successfully invoke this target.

```
‘make install-strip’
```

The ‘install-strip’ [automake\(1\)](#) target will install all the components of the package, but will strip unnecessary information out of the objects and compress manual pages. Root privilege is required to successfully invoke this target.

## 6.6 Removing

### 6.6.1 Removing the Binary RPM

To remove an installed version of the binary RPMs (whether obtained from the OpenSS7 binary RPM releases, or whether created by the source RPM), execute the following command:

```
% rpm -evv ‘rpm -qa | grep ‘^strsock-’‘
```

For more information see [rpm\(1\)](#).

### 6.6.2 Removing the Debian DEB

To remove and installed version of the Debian DEB (whether obtained from the OpenSS7 binary DEB releases, or whether created by the Debian DSC), execute the following command:

```
% dpkg -ev 'dpkg -l | grep '^strsock-'
```

For more information see [dpkg\(8\)](#).

### 6.6.3 Removing the Source RPM

To remove all the installed binary RPM build from the source RPM, see [Section 6.6.1 \[Removing the Binary RPM\]](#), page 76. Then simply remove the binary RPM package files and source RPM file. A command such as:

```
% find / -name 'strsock-*.rpm' -type f -print0 | xargs --null rm -f
```

should remove all 'strsock' RPMs from your system.

### 6.6.4 Removing the Debian DSC

To remove all the installed binary DEB build from the Debian DSC, see [Section 6.6.2 \[Removing the Debian DEB\]](#), page 76. Then simply remove the binary DEB package files and Debian DSC file. A command such as:

```
% find / \( -name 'strsock-*.deb' \  
    -o -name 'strsock-*.dsc' \  
    -o -name 'strsock-*.tar.*' \  
    \) -type f -print0 | xargs --null rm -f
```

should remove all 'strsock' DEBs, DSCs and TARs from your system.

### 6.6.5 Removing the Tar Ball

To remove a version installed from tar ball, change to the build directory where the package was built and use the 'uninstall' [automake\(1\)](#) target as follows:

```
% cd /usr/src/strsock  
% make uninstall  
% cd ..  
% rm -fr strsock-0.9.2.4  
% rm -f strsock-0.9.2.4.tar.gz  
% rm -f strsock-0.9.2.4.tar.bz2
```

If you have inadvertently removed the build directory and, therefore, no longer have a configured directory from which to execute 'make uninstall', then perform all of the steps for configuration and installation (see [Section 6.5.3 \[Installing the Tar Ball\]](#), page 76) except the final installation and then perform the steps above.

## 6.7 Loading

### 6.7.1 Normal Module Loading

When OpenSS7 STREAMS Sockets installs, modules and drivers belonging to release packages are normally configured for demand loading. The 'install' and 'install-strip'

`automake(1)` targets will make the necessary changes to the `/etc/modules.conf` file and place the modules in an appropriate place in `/lib/modules/2.4.20-28.7/strsock`. The `make install` process should have copied the kernel module files `streams-*.o` to the directory `/lib/modules/2.4.20-28.7/strsock`. This means that to load any of these modules, you can simply execute, for example, `modprobe stream-somedriver`.<sup>37</sup>

### 6.7.1.1 Linux Fast-STREAMS Module Loading

The `strsock` demand load system supports both the old `kerneld` and the new `kmod` mechanisms for demand loading kernel modules.

The convention for `strsock` kernel loadable object files is:

- Their name start with "streams-".
- They are placed in `/lib/modules/2.4.20-28.7/streams/`, where `2.4.20-28.7` is an example kernel version.

If your kernel has been built using the `kerneld` daemon, then `strsock` kernel modules will automatically load as soon as the *STREAMS* module is pushed or the driver is opened. The `make install` process makes the necessary changes to the `/etc/modules.conf` file. After the install, you will see lines like the following added to your `/etc/modules.conf` file:

```
prune modules.strsock
if -f /lib/modules/`uname -r`/modules.strsock
include /lib/modules/`uname -r`/modules.strsock
endif
```

which will provide for demand loading of the modules if they have been built and installed for the running kernel. The `/lib/modules/`uname -r`/modules.strsock` file looks like this:

```
alias char-major-245 streams-some_driver
alias char-major-246 streams-other_driver
```

Note that *STREAMS* modules are not listed in this file, but will be loaded by name using `kerneld` if available.

*Linux Fast-STREAMS* has a wider range of kernel module loading mechanisms than is provided by the deprecated *LiS*. For mechanisms used for kernel module loading under *Linux Fast-STREAMS*, See [Section "Top" in \*Linux Fast-STREAMS Reference Manual\*](#).

### 6.7.1.2 Linux STREAMS Module Loading

*LiS* is deprecated and this section has been deleted.

## 6.8 Maintenance

<sup>37</sup> Note that the `_kversion` of `2.4.20-28.7` is only an example.

## 6.8.1 Makefile Targets

`automake(1)` has many targets, not all of which are obvious to the casual user. In addition, *OpenSS7 automake(1)* files have additional rules added to make maintaining and releasing a package somewhat easier. This list of targets provides some help with what targets can be invoked, what they do, and what they hope to achieve. The available targets are as follows:

### 6.8.1.1 User Targets

The following are normal targets intended to be invoked by installers of the package. They are concerned with compiling, checking the compile, installing, checking the installation, and removing the package.

`[all]` This is also the default target. It compiles the package and all release packages selected by `configure`. This is performed after configuring the source with `configure`. A `Makefile` stub is provided so that if the package has not had `autoreconf(1)` run (such as when checked out from CVS, the package will attempt to run `autoreconf -fiv`).

All *OpenSS7 Project* packages are configured without maintainer mode and without dependency tracking by default. This speeds compilation of the package for one-time builds. This also means that if you are developing using the source package (edit-compile-test cycle), changes made to source files will not cause the automatic rebuilding due to dependencies. There are two ways to enable dependency tracking: specify `--enable-maintainer-mode` to `configure`; or, specify `--enable-dependency-tracking` to `configure`. I use the former during my edit-compile-test cycle.

This is a standard *GNU automake(1)* makefile target. This target does not require root privilege.

`check` All *OpenSS7 Project* release packages provide check scripts for the check target. This step is performed after compiling the package and will run all of the `check` programs against the compiled binaries. Which checks are performed depends on whether `--enable-maintainer-mode` was specified to `configure`. If in maintainer mode, checks that assist with the release of the package will be run (such as checking that all manual pages load properly and that they have required sections.) We recommend running the check stage before installing, because it catches problems that might keep the installed package from functioning properly.

Another way to enable the greater set of checks, without invoking maintainer mode, is to specify `--enable-checks` to `configure`. For more information, see [Section 7.1.1 \[Pre-installation Checks\], page 89](#).

This is a standard *GNU automake(1)* makefile target, although the functions performed are customized for the *OpenSS7 Project*. This target does not require root privilege.

`install`

`install-strip`

The `install` target installs the package by installing each release package. This target also performs some actions similar to the pre- and post-install scripts



used by packaging tools such as `rpm(1)` or `dpkg(1)`. The `'install-strip'` target strips unnecessary symbols from executables and kernel modules before installing.

This is a standard GNU `automake(1)` makefile target. This target requires root privilege.

#### `'installcheck'`

All *OpenSS7 Project* packages provide test scripts for the `'installcheck'` target. Test scripts are created and run using `autotest` (part of the `autoconf(1)` package). Which test suites are run and how extensive they are depends on whether `'--enable-maintainer-mode'` was specified to `'configure'`. When in maintainer mode, all test suites will be run. When not in maintainer mode, only a few post-install checks will be performed, but the test suites themselves will be installed in `'/usr/libexec/strsock'`<sup>38</sup> for later use.

This is a standard GNU `automake(1)` makefile target. This target might require root privilege. Tests requiring root privilege will be skipped when run as a regular user. Tests requiring regular account privileges will be skipped when run as root.

#### `'retest'`

To complement the `'installcheck'` target above, all *OpenSS7 Project* packages provide the `'retest'` target as a means to rerun failed conformance test suite test cases. The `'retest'` target is provided because some test cases in the test suites have delicate timing considerations that allow them to fail sporadically. Invoking this target will retest the failed cases until no cases that are not expected failures remain.

This is an *OpenSS7 Project* specific makefile target. As with `'installcheck'`, this target might require root privilege. Tests requiring root privilege will be skipped when run as a regular user. Tests requiring regular account privileges will be skipped when run as root.

#### `'uninstall'`

This target will reverse the steps taken to install the package. This target also performs pre- and post- erase scripts used by packaging tools such as `rpm` or `dpkg`. You need to have a configured build directory from which to execute this target, however, you do not need to have compiled any of the files in that build directory.<sup>39</sup>

The `'uninstall'` target unfortunately removes add-on packages in the same order in which they were installed. This is not good for the *OpenSS7 Master Package*, where the `'remove'` target should be used instead.

This is a standard GNU `automake(1)` makefile target. This target requires root privilege.

#### `'remove'`

This target is like `'uninstall'` with the exception that it removes add-on packages in the reverse order that installation was performed.<sup>40</sup>

<sup>38</sup> `'/usr/libexec/strsock'` is just an example, the actual location is `'${libexecdir}/${PACKAGE}'`, which varies from distribution to distribution (as some distributions such as Mandriva do not have a libexec directory).

<sup>39</sup> Therefore, it is possible to download the package, configure it, and then uninstall it. This is handy if you do not have the sources used to build and install the package immediately available.

<sup>40</sup> This is useful from the *OpenSS7 Master Package*.



This is an *OpenSS7 Project* specific makefile target. This target requires root privilege.

### 6.8.1.2 Maintainer Targets

The following targets are targets intended for use by maintainers of the package, or those responsible for release and packaging of a derivative work of the package. Some of these targets are only effective when maintainer mode has been invoked (`'--enable-maintainer-mode'` specified to `'configure'`.)

`'dist'` Creates a distribution package (tarball) in the top level build directory. *OpenSS7 Project* packages distribute two archives: a `'gzip tar'` archive and a `'bzip tar'` archive. These archives will have the name `'strsock-0.9.2.4.tar.gz'` and `'strsock-0.9.2.4.tar.bz2'`.

This is a standard *GNU automake(1)* makefile target. This target does not require root privilege.

`'distcheck'`

This target is intended for use when releasing the package. It creates the `tar(1)` archives above and then unpacks the tarball in a source directory, configures in a separate build directory, compiles the package, installs the package in a separate install directory, tests the install package to ensure that some components work, and, finally, uses the unpacked source tree to build another tarball. If you have added or removed files from the package, this is a good way to ensure that everything is still stable for release.

This is a standard *GNU automake(1)* makefile target. This target does not require root privilege.

### 6.8.1.3 Clean Targets

`'mostlyclean'`

Cleans out most of the files from the compile stage. This target is helpful if you have not enabled dependency tracking and need to recompile with changes.

This is a standard *GNU automake(1)* makefile target. This target does not require root privilege.

`'clean'`

Cleans all the files from the build directory generated during the `'make [all]'` phase. It does not, however, remove files from the directory left there from the `'configure'` run. Use the `'distclean'` target to remove those too.

This is a standard *GNU automake(1)* makefile target. This target might require root privilege if the `'installcheck'` target or the `testsuite` was invoked with root privilege (leaving files belonging to root).

`'distclean'`

This target cleans out the directories left behind by `'distcheck'` and removes all the `'configure'` and generated files from the build directory. This will effectively remove all the files in the build directory, with the except of files that belong to you or some other process.

This is a standard *GNU automake(1)* makefile target. This target might require root privilege if the ‘installcheck’ target or the `testsuite` was invoked with root privilege (leaving files belonging to root).

**‘maintainer-clean’**

This target not only removes files from the build directory, it removes generated files from the source directory as well. Care should be taken when invoking this target, because it removes files generated by the maintainer and distributed with the archive that might require special tools to regenerate. These special tools might only be available to the maintainer.<sup>41</sup> It also means that you probably need a full blown Linux system to rebuild the package. For more information, see [Section 6.2.8 \[Downloading from CVS\], page 55](#).

This is a standard *GNU automake(1)* makefile target. This target might require root privilege if the ‘installcheck’ target or the `testsuite` was invoked with root privilege (leaving files belonging to root).

**‘check-clean’**

This target removes log files left behind by the ‘check’ target. By default, the check scripts append to log files in the top level build directory. This target can be used to clean out those log files before the next run.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

### 6.8.1.4 Manual Page Targets

The following targets are used to build, install and uninstall just the manual pages from the distribution. These targets are good for creating a distribution of just the manual pages. When building atop multiple packages, these targets recurse down through each package.

**‘mans’** Build all of the manual pages. This involves performing parameter substitution on manual pages and optionally cooking the manual pages if ‘--with-cooked-manpages’ was requested during configuration.

**‘install-mans’**

Installs the manual pages under *DESTDIR*. Specify *DESTDIR* to place the manual pages wherever you see fit. If *DESTDIR* is not specified on the command line, the manual pages will be installed in the normal installation directory.

**‘uninstall-mans’**

Uninstalls the manual pages from *DESTDIR*. Specify *DESTDIR* to indicate where to remove the manual pages from. If *DESTDIR* is not specified on the command line, the manual pages will be removed from the normal installation directory.

### 6.8.1.5 Release Targets

The following are targets used to generate complete releases into the package distribution directory. These are good for unattended and NFS builds, which is what I use them for.

---

<sup>41</sup> Theoretically this is true, however, the *OpenSS7 Project* does not use any maintainer programs that are not generally available (i.e. open source).

Also, when building from atop multiple packages, these targets also recurse down through each package.

**‘release’** Build all of the things necessary to generate a release. On an `rpm(1)` system this is the distribution archives, the source rpm, and the architecture dependent and architecture independent binary rpms. All items are placed in the package distribution directory that can be specified with the `‘--with-pkg-distdir=DIR’` option to `‘configure’`.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘forced-release’**

The `‘release’` target will not regenerate any files that already exist in the package distribution directory. This forced target will.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘release-sign’**

You will be prompted for a password, unless to specify it to make with the `GNUPGPASS` variable. For unattended or non-interactive builds with signing, you can do that as: `‘make GNUPGPASS=myspasswd release-sign’`

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘forced-release-sign’**

The `‘release-sign’` target will not regenerate any files that already exist in the package distribution directory. This forced target will.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘release-clean’**

This target will remove all distribution files for the current package from the package distribution directory.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

### 6.8.1.6 Logging Targets

For convenience, to log the output of a number of targets to a file, log targets are defined. The log file itself is used as the target to make, but make invokes the target minus a `‘.log’` suffix. So, for example, to log the results of target `‘foo’`, invoke the target `‘foo.log’`. The only target that this does not apply to is `‘compile.log’`. When you invoke the target `‘compile.log’` a simple `automake(1)` is invoked and logged to the file `‘compile.log’`. The `‘foo.log’` rule applies to all other targets. This does not work for all targets, just a selected few.<sup>42</sup> Following are the logging targets:

<sup>42</sup> Note that because logging targets invoke a pipe, `automake(1)` does not return the correct return status (always returns success if the `tee(1)` operation is successful). Therefore, these targets should not be invoked by scripts that need to use the return value from `automake(1)`.

## Common Logging Targets

Common logging targets correspond to normal user `automake(1)` makefile targets as follows:

`'compile.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'[all]'`.

`'check.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'check'`.

`'install.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'install'`.

`'installcheck.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'installcheck'`.

`'uninstall.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'uninstall'`.

`'remove.log'`

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* `'remove'` target.

## Maintainer Logging Targets

Maintainer logging targets correspond to maintainer mode `automake(1)` makefile targets as follows:

`'dist.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'dist'`.

`'distcheck.log'`

This is an *OpenSS7 Project* specific makefile target, but it invokes the standard GNU `automake(1)` makefile target `'distcheck'`.

`'srpm.log'`

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* `'srpm'` target.

`'rebuild.log'`

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* `'rebuild'` target.

`'resign.log'`

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* `'resign'` target.

`'release.log'`

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* `'release'` target.

**‘release-sign.log’**

This is an *OpenSS7 Project* specific makefile target, that invokes the *OpenSS7 Project* ‘release-sign’ target.

If you want to add one, simply add it to *LOGGING\_TARGETS* in ‘Makefile.am’.

**6.8.1.7 Problem Report Targets**

To ease problem report generation, all logging targets will automatically generate a problem report suitable for mailing in the file ‘target.pr’ for target ‘target.log’. This problem report file is in the form of an email and can be sent using the included `send-pr` script or by invoking the ‘send-pr’ makefile target.

There are two additional problem report targets:

**‘pr’**

The ‘pr’ target is for independently generating a problem report outside of the build or installation process. The target will automatically generate a problem report skeleton suitable for editing and mailing in the file ‘problem.pr’. This problem report file is in the form of an email and can be edited and sent directly, or sent using the included `send-pr` script or by invoking the ‘send-pr’ target. This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘send-pr’**

The ‘send-pr’ target is for finalizing and mailing a problem report generated either inside or outside the build and installation process. The target will automatically finalize and mail the ‘problem.pr’ problem report if it has changed since the last time that ‘send-pr’ was invoked.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege (unless the problem report file was generated as root).

**6.8.1.8 Release Archive Targets**

The following targets are used to generate and clean distribution archive and signature files. Whereas the ‘dist’ target affects archives in the top build directory, the ‘release-archive’ targets affects archives in the package distribution directory (either the top build directory or that specified with ‘--with-pkg-distdir=DIR’ to ‘configure’).

You can change the directory to which packages are distributed by using the ‘--with-pkg-distdir=DIR’ option to ‘configure’. The default directory is the top build directory.

**‘release-archives’**

This target creates the distribution archive files if they have not already been created. This not only runs the ‘dist’ target, but also copies the files to the distribution directory, which, by default is the top build directory.

The files generated are named:

‘strsock-0.9.2.4.tar.gz’ and ‘strsock-0.9.2.4.tar.bz2’

You can change this distribution directory with the ‘--with-pkg-distdir’ option to ‘configure’. See ‘./configure --help’ for more details on options.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘release-sign-archives’**

This target is like ‘release-archives’, except that it also signs the archives using a *GPG* detached signature. You will be prompted for a password unless you pass the *GNUPGPASS* variable to make. For automated or unattended builds, pass the *GNUPGPASS* variable like so:

```
‘make GNUPGPASS=mypasswd release-sign-archives’
```

Signature files will be named:

```
‘strsock-0.9.2.4.tar.gz.asc’ and ‘strsock-0.9.2.4.tar.bz2.asc’
```

These files will be moved to the package distribution directory with the plain text archives.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘release-clean-archives’**

This target will clean the release archives and signature files from the package distribution directory.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

### 6.8.1.9 RPM Build Targets

On **rpm(1)** systems, or systems sporting rpm packaging tools, the following targets are used to generate **rpm(1)** release packages. The epoch and release number can be controlled by the contents of the ‘.rpmepoch’ and ‘.rpmrelease’ files, or with the ‘--with-rpm-epoch=EPOCH’ and ‘--with-rpm-release=RELEASE’ options to ‘configure’. See ‘configure --help’ for more information on options. We always use release number ‘1’. You can use release numbers above ‘1’.

**‘srpm’** This target generates the source rpm for the package (without signing the source rpm). The source rpm will be named: ‘strsock-0.9.2.4-1.srpm’.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘rpms’** This target is responsible for generating all of the package binary rpms for the architecture. The binary rpms will be named:

```
‘strsock-*-0.9.2.4-1.*.rpm’
```

where the stars indicate the subpackage and the architecture. Both the architecture specific subpackages (binary objects) and the architecture independent (‘.noarch’) subpackages will be built unless the the former was disabled with the option ‘--disable-arch’, or the later with the option ‘--disable-indep’, passed to ‘configure’.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**‘sign’****‘srpm-sign’**

These two targets are the same. When invoked, they will add a signature to the source rpm file, provided that the file does not already have a signature.

You will be prompted for a password if a signature is required. Automated or unattended builds can be achieved by using the `emake` expect script, included in `'${srcdir}/scripts/emake'`.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**'rebuild'** This target searches out a list of kernel names from the `'${DESTDIR}/lib/modules'` directory and builds rpms for those kernels and for each of a set of architectures given in the `AM_RPMTARGETS` variable to make. This is convenience target for building a group of rpms on a given build machine.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**'resign'** This target will search out and sign, with a *GPG* signature, the source rpm, and all of the binary rpms for this package that can be found in the package distribution directory. This target will prompt for a *GPG* password. Automated or unattended builds can be achieved with the `emake` expect script located here: `'${srcdir}/scripts/emake'`.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

### 6.8.1.10 Debian Build Targets

On Debian systems, or systems sporting Debian packaging tools, the following targets are used to generate Debian release packages. The release number can be controlled by the contents of the `.debrelease` file, or with the `--with-debrelease=RELEASENUMBER` option to `configure`. See `configure --help` for more information on options.

**'dsc'** This target will build the Debian source change package (`.dsc` file). We use release number `'0'` so that the entire tarball is included in the `'dsc'` file. You can use release number `'1'` for the same purposes. Release numbers above `'1'` will not include the entire tarball. The `.dsc` file will be named: `'strsock_0.9.2.4-0.dsc'`.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**'sigs'** This target signs the `.deb` files. You will be prompted for a password, unless to specify it to make with the `GNUPGPASS` variable.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

**'debs'** This target will build the Debian binary package (`.deb` file) from the `.dsc` created above. (This target will also create the `.dsc` if it has not been created already.) The subpackage `.deb` files will be named: `'strsock-*_0.9.2.4-0_*.deb'`, where the stars indicate the subpackage and the architecture.

This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

`'csig'` This target signs the `'dsc'` file. You will be prompted for a password, unless to specify it to make with the `GNUPGPASS` variable.  
This is an *OpenSS7 Project* specific makefile target. This target does not require root privilege.

### 6.8.1.11 Documentation Targets

On systems that have `doxygen(1)` documentation tool, the following targets are used to generate doxygen html documentation:

`'doxy'` This target generates `doxygen(1)` documetnation from suitably marked sources. File containing the necessary documentation marks are discovered automatically by `configure`. Doxygen documentation can be generated bus is not distributed. Documentation is cerated in the subdirectory `'doc/html'`.



## 7 Troubleshooting

### 7.1 Test Suites

#### 7.1.1 Pre-installation Checks

Most *OpenSS7* packages, including the *OpenSS7 STREAMS Sockets* package, ship with pre-installation checks integral to the build system. Pre-installation checks include check scripts that are shipped in the ‘scripts’ subdirectory as well as specialized `make` targets that perform the checks.

When building and installing the package from *RPM* or *DEB* source packages (see [Section 6.4.1 \[Building from the Source RPM\]](#), page 73; and [Section 6.4.2 \[Building from the Debian DSC\]](#), page 74), a fundamental set of post-compile, pre-installation checks are performed prior to building binary packages. This is performed automatically and does not require any special actions on the part of the user creating binary packages from source packages.

When building and installing the package from *tarball* (see [Section 6.4.3 \[Building from the Tar Ball\]](#), page 74; and [Section 6.5.3 \[Installing the Tar Ball\]](#), page 76), however, pre-installation checks are only performed if specifically invoked by the builder of the package. Pre-installation checks are invoked after building the package and before installing the package. Pre-installation checks are performed by invoking the ‘check’ or ‘check.log’ target to `make` when building the package, as shown in [Example 7.1](#).

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure
% make
% make check # <----- invoke pre-installation checks
% popd
```

Example 7.1: *Invoking Pre-Installation Checks*

Pre-installation checks fall into two categories: *System Checks* and *Maintenance Checks*.

##### 7.1.1.1 Pre-Installation System Checks

*System Checks* are post-compilation checks that can be performed before installing the package that check to ensure that the compiled objects function and will be successfully installed. When the ‘--enable-maintainer-mode’ option has not been passed to `configure`, only *System Checks* will be performed.

For example, the steps shown in [Example 7.2](#) will perform *System* checks.

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure
% make
% make check # <----- invokes System pre-installation checks
% popd
```

Example 7.2: *Invoking System Checks*

### 7.1.1.2 Pre-Installation Maintenance Checks

*Maintenance Checks* include all *System Checks*, but also checks to ensure that the kernel modules, applications programs, header files, development tools, test programs, documentation, and manual pages conform to *OpenSS7* standards. When the ‘`--enable-maintainer-mode`’ option has been passed to `configure`, *Maintenance Checks* will be performed.

For example, the steps shown in [Example 7.3](#) will perform *Maintenance* checks.

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure --enable-maintainer-mode
% make
% make check # <----- invokes Maintenance pre-installation checks
% popd
```

Example 7.3: *Invoking Maintenance Checks*

### 7.1.1.3 Specific Pre-Installation Checks

A number of check scripts are provided in the ‘`scripts`’ subdirectory of the distribution that perform both *System* and *Maintenance* checks. These are as follows:

#### `check_commands`

This check performs both *System* and *Maintenance* checks.

When performing *System* tests, the following tests are performed:

Unless cross-compiling, or unless a program is included in `AM_INSTALLCHECK_STD_OPTIONS_EXEMPT` every program in `bin_PROGRAMS`, `sbin_PROGRAMS`, and `libexec_PROGRAMS` is tested to ensure that the ‘`--help`’, ‘`--version`’, and ‘`--copying`’ options are accepted. When cross-compiling is not possible to execute cross-compiled binaries, and these checks are skipped in that case.

Script executables, on the other hand, can be executed on the build host, so, unless listed in `AM_INSTALLCHECK_STD_OPTIONS_EXEMPT`, every program in `dist_bit_SCRIPTS`, `dist_sbin_SCRIPTS`, and `pkglibexec_SCRIPTS` are tested to ensure that the ‘`--help`’, ‘`--version`’, and ‘`--copying`’ options are accepted.

When performing *Maintenance* tests, `check_commands` also checks to ensure that a manual page exists in section 1 for every executable binary or script

that will be installed from `bin_PROGRAMS` and `dist_bin_SCRIPTS`. It also checks to ensure that a manual page exists in section 8 for every executable binary or script that will be installed from `sbin_PROGRAMS`, `dist_sbin_SCRIPTS`, `libexec_PROGRAMS`, and `pkglibexec_SCRIPTS`.

#### `check_decls`

This check only performs *Maintenance* checks.

It collects the results from the `check_libs`, `check_modules` and `check_headers` check scripts and tests to ensure every declaration of a function prototype or external variable contained in installed header files has a corresponding exported symbol from either a to be installed shared object library or a to be installed kernel module. Declarations are exempted from this requirement if their identifiers have been explicitly added to the `EXPOSED_SYMBOL` variable. If `WARN_EXCESS` is set to 'yes', then the check script will only warn when excess declarations exist (without a corresponding exported symbol); otherwise, the check script will generate an error and the check will fail.

#### `check_headers`

This check only performs *Maintenance* checks.

When performing *Maintenance* tests, it identifies all of the declarations included in to be installed header files. It then checks to ensure that a manual page exists in sections 2, 3, 7 or 9, as appropriate, for the type of declaration. It also checks to see if a manual page source file exists in the source directory for a declaration that has not been included in the distribution. Function or prototype declarations that do not have a manual page in sections 2, 3, or 9 will cause the check to fail. Other declarations ('variable', 'externvar', 'macro', 'enumerate', 'enum', 'struct', 'union', 'typedef', 'member', etc.) will only warn if a manual page does not exist, but will not fail the check.

#### `check_libs`

This check only performs *Maintenance* checks.

When performing *Maintenance* tests, it checks that each exported symbol in each to be installed shared object library has a manual page in section 3. It also checks that each exported symbol has a 'function', 'prototype' or 'externvar' declaration in the to be installed header files. A missing declaration or manual page will cause this check to fail.

#### `check_mans`

This check only performs *Maintenance* checks.

When performing *Maintenance* tests, it checks that to be install manual pages can be formatted for display without any errors or warnings from the build host `man` program. It also checks that required headings exist for manual pages according to the section in which the manual page will be installed. It warns if recommended headings are not included in the manual pages. Because some *RPM* distributions have manual pages that might conflict with the package manual pages, this check script also checks for conflicts with installed manual pages on the build host. This check script also checks to ensure that all to be

installed manual pages are used in some fashion, that is, they have a declaration, or exported symbol, or are the name of a kernel module or STREAMS module or driver, possibly capitalized.

Note that checking for conflicts with the build host should probably be included in the *System* checks (because *System* checks are performed before the source *RPM %install* scriptlet).

#### check\_modules

This check performs both *System* and *Maintenance* checks.

When performing *System* tests, it checks each to be installed kernel module to ensure that all undefined symbols can be resolved to either the kernel or another module. It also checks whether an exported or externally declared symbol conflicts with an exported or externally declared symbol present in the kernel or another module.<sup>1</sup>

When performing *Maintenance* tests, this check script tests that each to be installed kernel module has a manual page in section 9 and that each exported symbol that does not begin with an underscore, and that belongs to an exported function or exported variable, has a manual page in section 9. It also checks to ensure that each exported symbol that does not begin with an underscore, and that belongs to an exported function or exported variable, has a ‘function’, ‘prototype’ or ‘externvar’ declaration in the to be installed header files.

#### check\_streams

This check performs only *Maintenance* checks.

When performing *Maintenance* tests, it checks that for each configured *STREAMS* module or driver, or device node, that a manual page exists in section 4 or section 7 as appropriate.

The output of the pre-installation tests are fairly self explanatory. Each check script saves some output to ‘*name.log*’, where *name* is the name of the check script as listed above. A summary of the results of the test are display to standard output and can also be captured to the ‘check.log’ file if the ‘check.log’ target is used instead of the ‘check’ target to *make*.

Because the check scripts proliferate ‘*name.log*’ files throughout the build directory, a ‘*make check-clean*’ *make* target has be provided to clean them out. ‘*make check-clean*’ should be run before each successive run of ‘*make check*’.

### 7.1.2 Post-installation Checks

Most OpenSS7 packages ship with a compatibility and conformance test suite built using the ‘autotest’ capabilities of ‘autoconf’. These test suites act as a wrapper for the compatibility and conformance test programs that are shipped with the package.

Unlike the pre-installation checks, the post-installation checks are always run complete. The only check that post-installation test scripts perform is to test whether they have been invoked with root privileges or not. When invoked as root, or as a plain user, some tests might be skipped that require root privileges, or that require plain user privileges, to complete successfully.

<sup>1</sup> This particular check has caught some name space pollution that has occurred in the 2.6.11 kernel.

### 7.1.2.1 Running Test Suites

There are several ways of invoking the conformance test suites:

1. The test suites can be run after installation of the package by invoking the `make installcheck` or `make installcheck.log` target. Some packages require that root privileges be acquired before invoking the package.
2. The test suites can be run from the distribution subdirectory after installation of the package by invoking the `testsuite` shell script directly.
3. The test suites can be run standalone from the `libexec` (`/usr/libexec`) installation directory by invoking the `testsuite` shell script directly.

Typical steps for invoking the test suites directly from `make` are shown in [Example 7.4](#).

```
% wget http://www.openss7.org/strsock-0.9.2.4.tar.bz2
% tar -xjvf strsock-0.9.2.4.tar.bz2
% pushd strsock-0.9.2.4
% ./configure
% make
% make check # <----- invokes System pre-installation checks
% make install
% sudo make installcheck # <----- invokes post-installation tests
% popd
```

Example 7.4: *Invoking System Checks*

When performing post-installation checks for the purposes of generating a problem report, the checks should always be performed from the build directory, either with `make installcheck` or by invoking `testsuite` directly from the `tests` subdirectory of the build directory. This ensures that all of the information known to `configure` and pertinent to the configuration of the system for which a test case failed, will be collected in the resulting `testsuite.log` file deposited upon test suite failure in the `tests` directory. This `testsuite.log` file can then be attached as part of the problem report and provides rich details to maintainers of the package. See also [Section 7.2 \[Problem Reports\]](#), page 93, below.

Typical steps for invoking and installed `testsuite` standalone are shown in [Example 7.5](#).

```
% [sudo] /usr/libexec/strsock/testsuite
```

Example 7.5: *Invoking testsuite Directly*

When invoked directly, `testsuite` will generate a `testsuite.log` file in the current directory, and a `testsuite.dir` directory of failed tests cases and debugging scripts. For generating a problem report for failed test cases, see [Section 7.2.4 \[Stand Alone Problem Reports\]](#), page 96.

## 7.2 Problem Reports

### 7.2.1 Problem Report Guidelines

Problem reports in the following categories should include a log file as indicated in the table below:

`./configure`

A problem with the configuration process occurs that causes the `./configure` command to fail. The problem report must include the `config.log` file that was generated by `configure`.

`make compile.log`

A problem with the build process occurs that causes the `make` command to fail. Perform `make clean` and then `make compile.log` and attach the `config.log` and `compile.log` files to the problem report.

`make check.log`

A problem occurs with the `make check` target that causes it to fail. Perform `make check-clean check.log` and attach the `config.log`, `compile.log` and `check.log` files to the problem report.

`sudo make install.log`

A problem occurs with `sudo make install` that causes it to fail. Perform `sudo make uninstall` and `sudo make install.log` and attach the `config.log`, `compile.log`, `check.log`, and `install.log` files to the problem report.

`[sudo] make installcheck.log`

A problem occurs with the `make installcheck` target that causes the test suite to fail. Attach the resulting `tests/testsuite.log` and `installcheck.log` file to the problem report. There is no need to attach the other files as they are included in `tests/testsuite.log`.

`[sudo] make uninstall.log`

A problem occurs with the `make uninstall` target that causes the test suite to fail. Perform `sudo make uninstall.log` and attach the `config.log`, `compile.log`, `check.log`, `install.log`, `installcheck.log`, `tests/testsuite.log` and `uninstall.log` file to the problem report.

`[sudo] make remove.log`

A problem occurs with the `make remove` target that causes the test suite to fail. Perform `sudo make remove.log` and attach the `config.log`, `compile.log`, `check.log`, `install.log`, `installcheck.log`, `tests/testsuite.log` and `remove.log` file to the problem report.

For other problems that occur during the use of the *OpenSS7 STREAMS Sockets* package, please write a test case for the test suite that recreates the problem if one does not yet exist and provide a test program patch with the problem report. Also include whatever log files are generated by the kernel (`cmn_err(9)`) or by the `strerr(8)` or `strace(1)` facilities (`strlog(9)`).

### 7.2.2 Generating Problem Reports

The *OpenSS7 Project* uses the *GNU GNATS* system for problem reporting. Although the `send-pr` tool from the *GNU GNATS* package can be used for bug reporting to the project's

*GNATS* database using electronic mail, it is not always convenient to download and install the *GNATS* system to gain access to the ‘send-pr’ tool.

Therefore, the *OpenSS7 STREAMS Sockets* package provides the ‘send-pr’ shell script that can be used for problem reporting. The ‘send-pr’ shell script can be invoked directly and is a work-alike for the *GNU* ‘send-pr’ tool.

The ‘send-pr’ tool takes the same flags and can be used in the same fashion, however, whereas ‘send-pr’ is an interactive tool<sup>2</sup>, ‘send-pr’ is also able to perform batch processing. Whereas ‘send-pr’ takes its field information from local databases or from using the ‘query-pr’ C-language program to query a remote database, the ‘send-pr’ tool has the field database internal to the tool.

Problem reports can be generated using *make*, See [Section 6.8.1.7 \[Problem Report Targets\]](#), [page 85](#). An example of how simple it is to generate a problem report is illustrated in [Example 7.6](#).

```
% make pr
SEND-PR:
SEND-PR: send-pr: send-pr was invoked to generate an external report. An
SEND-PR: automated problem report has been created in the file named
SEND-PR: 'problem.pr' in the current directory. This problem report can
SEND-PR: be sent to bugs@openss7.org by calling this script as
SEND-PR: '/home/brian/os7/scripts/send-pr --file="problem.pr"'.
SEND-PR:
SEND-PR: It is possible to edit some of the fields before sending on the
SEND-PR: problem report. Please remember that there is NO WARRANTY. See
SEND-PR: the file 'COPYING' in the top level directory.
SEND-PR:
SEND-PR: Please do not send confidential information to the bug report
SEND-PR: address. Inspect the file 'problem.pr' for confidential
SEND-PR: information before mailing.
SEND-PR:
% vim problem.pr # <--- follow instructions at head of file
% make send-pr
```

Example 7.6: *Invoking Problem Report Generation*

Using the ‘make pr’ target to generate a problem report has the advantages that it will assemble any available ‘\*.log’ files in the build directory and attach them to the problem report.

### 7.2.3 Automatic Problem Reports

The *OpenSS7 STREAMS Sockets* package also provides a feature for automatic problem report generation that meets the problem report submission guidelines detailed in the preceding sections.

Whenever a logging makefile target (see [Section 6.8.1.6 \[Logging Targets\]](#), [page 83](#)) is invoked, if the primary target fails, the *send-pr* shell script is invoked to automatically

<sup>2</sup> ‘send-pr’ launches the user’s *EDITOR* to edit the problem report before submitting it.



generate a problem report file suitable for the corresponding target (as described above under see [Section 7.2.1 \[Problem Report Guidelines\]](#), page 94). An example is shown in [Example 7.7](#).

```
% make compile.log
...
...
make[5]: *** [libXNSdrvs_a-ip.o] Error 1
make[5]: Leaving directory '/u6/buildel4/strxns'
make[4]: *** [all-recursive] Error 1
make[4]: Leaving directory '/u6/buildel4/strxns'
make[3]: *** [all] Error 2
make[3]: Leaving directory '/u6/buildel4/strxns'
make[2]: *** [all-recursive] Error 1
make[2]: Leaving directory '/u6/buildel4'
make[1]: *** [all] Error 2
make[1]: Leaving directory '/u6/buildel4'
SEND-PR:
SEND-PR: send-pr: Make target compile.log failed in the compile stage. An
SEND-PR: automated problem report has been created in the file named
SEND-PR: 'problem.pr' in the current directory. This problem report can
SEND-PR: be sent to bugs@openss7.org by calling 'make send-pr'.
SEND-PR:
SEND-PR: It is possible to edit some of the fields before sending on the
SEND-PR: problem report. Please remember that there is NO WARRANTY. See
SEND-PR: the file 'COPYING' in the top level directory.
SEND-PR:
SEND-PR: Please do not send confidential information to the bug report
SEND-PR: address. Inspect the file 'problem.pr' for confidential
SEND-PR: information before mailing.
SEND-PR:
% vim problem.pr # <--- follow instructions at head of file
% make send-pr
```

Example 7.7: *Problem Report from Failed Logging Target*

## 7.2.4 Stand Alone Problem Reports

The *OpenSS7 STREAMS Sockets* package installs the `send-pr` script and its configuration file `send-pr.config` in ``${libexecdir}/strsock` along with the validation `testsuite`, see [Section 7.1 \[Test Suites\]](#), page 89. As with the `testsuite`, this allows the `send-pr` script to be used for problem report generation on an installed system that does not have a build directory.

An example of invoking the package `testsuite` and then generating a problem report for failed cases is shown in [Example 7.8](#).



```

% [sudo] /usr/libexec/strsock/testsuite
% # test cases failed...
% /usr/libexec/strsock/send-pr
SEND-PR:
SEND-PR: send-pr: send-pr was invoked to generate an external report. An
SEND-PR: automated problem report has been created in the file named
SEND-PR: 'problem.pr' in the current directory. This problem report can
SEND-PR: be sent to bugs@openss7.org by calling this script as
SEND-PR: '/usr/libexec/strsock/send-pr --file problem.pr'.
SEND-PR:
SEND-PR: It is possible to edit some of the fields before sending on the
SEND-PR: problem report. Please remember that there is NO WARRANTY. See
SEND-PR: the file 'COPYING' in the top level directory.
SEND-PR:
SEND-PR: Please do not send confidential information to the bug report
SEND-PR: address. Inspect the file 'problem.pr' for confidential
SEND-PR: information before mailing.
SEND-PR:
% vim problem.pr # <--- follow instructions at head of file
% /usr/libexec/strsock/send-pr --file problem.pr

```

Example 7.8: *Invoking send-pr Directly*

The advantage of the approach shown in the example is that the `send-pr` script is capable of collecting the `testsuite.log` file and the failed test cases and debugging scripts from the `testsuite.dir` directory and including them in the problem report, as well as all package pertinent information from the installed `send-pr.config`.

### 7.3 Known Problems

*The OpenSS7 Project* does not ship software with known bugs. All bugs are unknown.

Verified behaviour is that behaviour that has been verified by conformance test suites that are shipped with the *OpenSS7 STREAMS Sockets* package.

Unverified behaviour may contain unknown bugs.

Please remember that there is **NO WARRANTY**.

See also [Section 5.5 \[Bugs\]](#), page 40, or file `BUGS` in the release directory.



## Appendix A Possible BSD Sources

It is possible that some of the software contained in the following files might be ultimately derived from the associated *BSD Net2* sources:

<i>OpenSS7 File</i>	<i>BSD Net2 File</i>
'src/drivers/socksys.c'	'usr/src/uts/i386/io/osocket.c'
'src/modules/sockmod.c'	'usr/src/uts/i386/io/sockmod.c'
'src/include/sys/sockmod.h'	'usr/src/uts/i386/sys/sockmod.h'
'src/include/sys/protosw.h'	'usr/src/uts/i386/sys/protosw.h'
'src/include/sys/socksys.h'	'usr/src/uts/i386/sys/osocket.h'
'src/include/sys/socket.h'	'usr/src/uts/i386/sys/socket.h'
'src/include/sys/socketvar.h'	'usr/src/uts/i386/sys/socketvar.h'
'src/include/sys/sockio.h'	'usr/src/uts/i386/sys/sockio.h'
'src/lib/sockets.c'	'usr/src/lib/libsocket/socket/_conn_util.c'
'src/lib/sockets.c'	'usr/src/lib/libsocket/socket/_utility.c'
'src/lib/accept.c'	'usr/src/lib/libsocket/socket/accept.c'
'src/lib/bind.c'	'usr/src/lib/libsocket/socket/bind.c'
'src/lib/connect.c'	'usr/src/lib/libsocket/socket/connect.c'
'src/lib/getpeername.c'	'usr/src/lib/libsocket/socket/getpeername.c'
'src/lib/getsockname.c'	'usr/src/lib/libsocket/socket/getsockname.c'
'src/lib/getsockopt.c'	'usr/src/lib/libsocket/socket/getsockopt.c'
'src/lib/listen.c'	'usr/src/lib/libsocket/socket/listen.c'
'src/lib/receive.c'	'usr/src/lib/libsocket/socket/receive.c'
'src/lib/ioctl.c'	'usr/src/lib/libsocket/socket/s_ioctl.c'
'src/lib/send.c'	'usr/src/lib/libsocket/socket/send.c'
'src/lib/setpeername.c'	'usr/src/lib/libsocket/socket/setpeername.c'
'src/lib/setsockname.c'	'usr/src/lib/libsocket/socket/setsockname.c'
'src/lib/setsockopt.c'	'usr/src/lib/libsocket/socket/setsockopt.c'
'src/lib/shutdown.c'	'usr/src/lib/libsocket/socket/shutdown.c'
'src/lib/socket.c'	'usr/src/lib/libsocket/socket/socket.c'
'src/lib/socketpair.c'	'usr/src/lib/libsocket/socket/socketpair.c'

The files on the right were listed in *Exhibit C* of *The 1994 USL-Regents of UCal Settlement Agreement* and are therefore possibly subject to the *USL/BSD Combined License* of *Exhibit F* (see [\[BSD/USL Combined License\]](#), page 113).



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Version 3, 29 June 2007

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